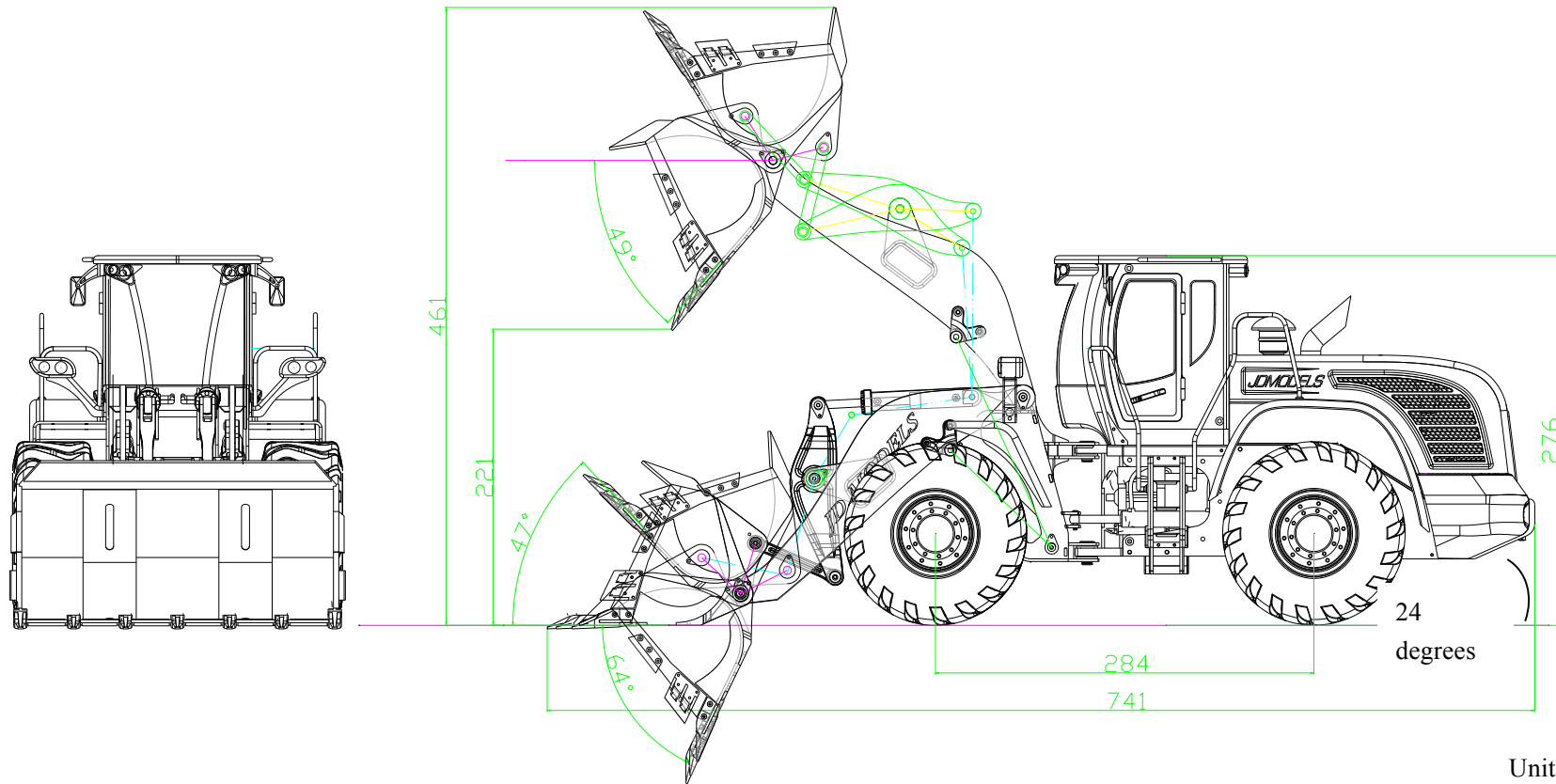


JDM-888III Hydraulic loader Model



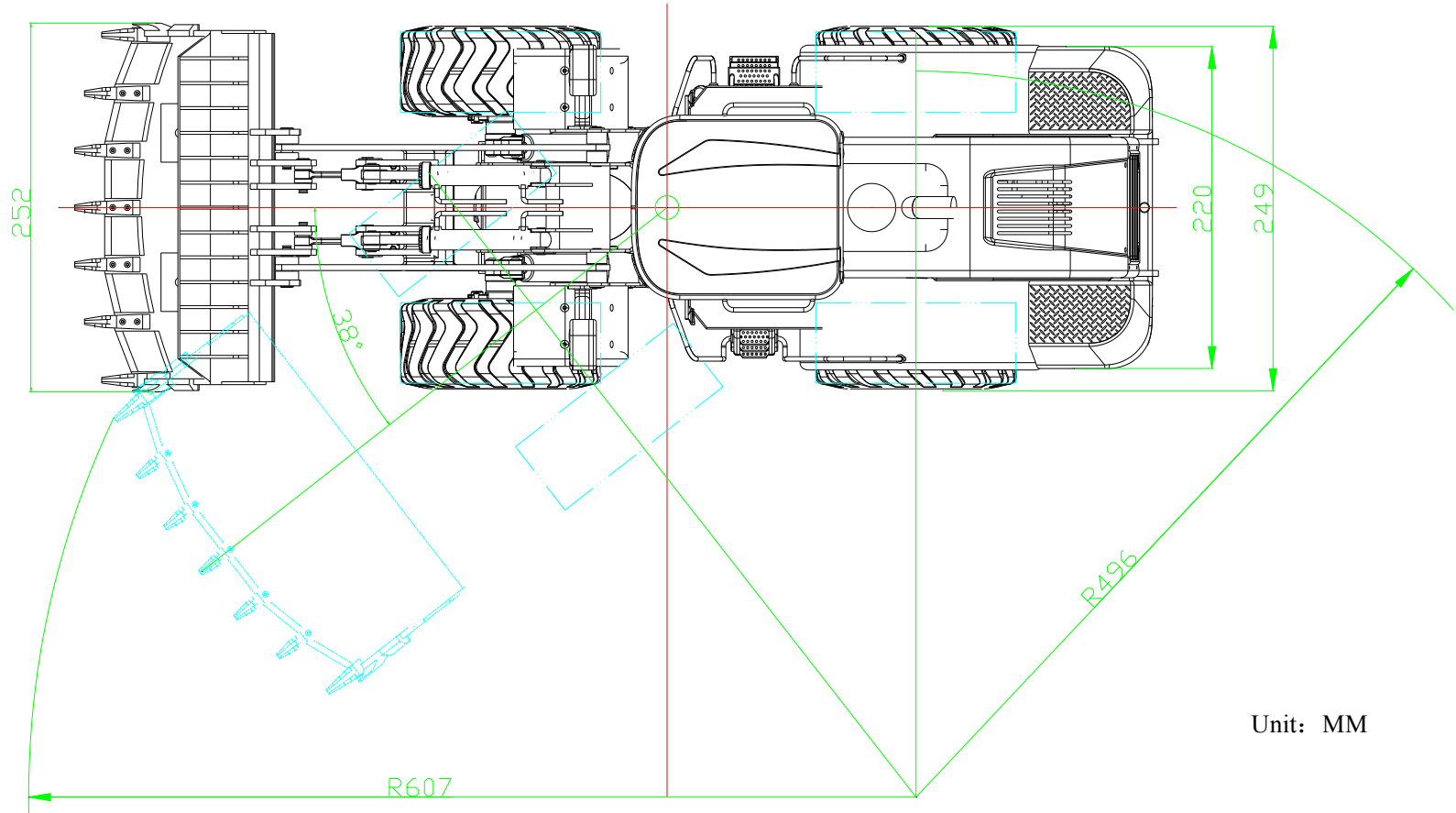
Scale: 1: 14 (Remote control, hydraulic installation)
Volume of bucket: 8T
Size: Length 741mm, Width 249mm, Height 276mm
Weight: 21KG
Digging force: 70kG
Remote control: WFLY 06X-A 2.4G



Unit: MM

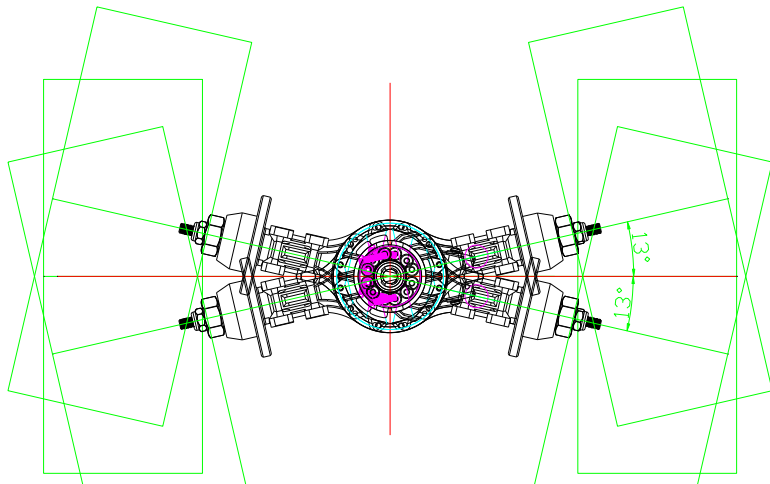
Maximum discharging bucket angle 49 degrees: Designed automatically flat function (Graphical Representation: after discharging, just need to make arm down, bucket will be automatically around 5 degrees flat to the surface with the shovel loading state). **Maximum collecting bucket angle 47 degrees:** Designed automatically translation function (Graphical Representation: after collecting bucket, just need to make arm move up, bucket will be automatically translated to the highest point, discharge state).

Discharge level: 221. Material maximum raise level: 461. Angle from the ground: 24 degrees. Maximum bucket height: 461mm/18inch

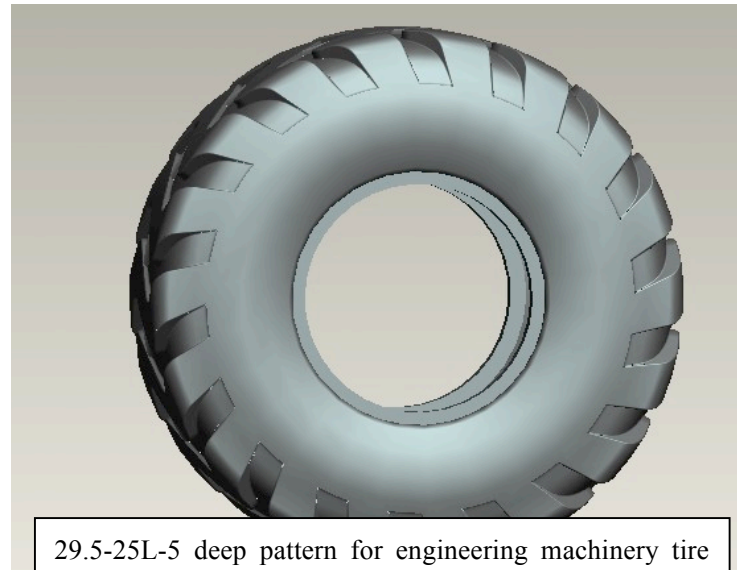


Unit: MM

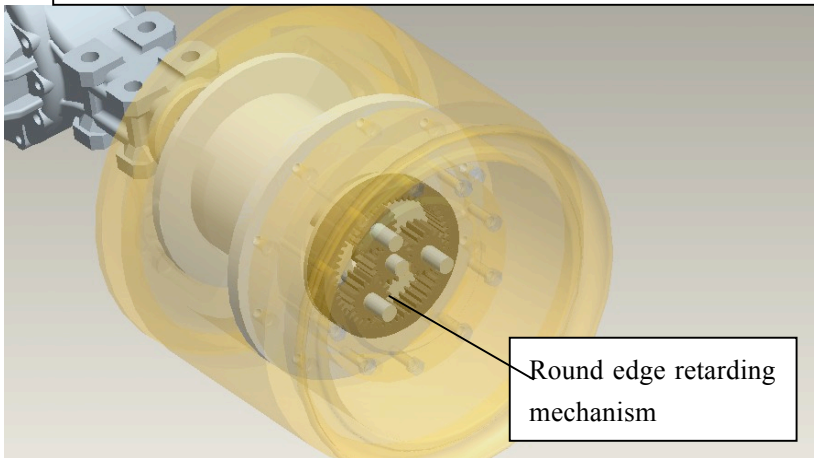
Hydraulic steering articulated frame design ± 38 degrees, bucket minimum turning radius: 607mm, tire center minimum turning radius: 496 mm



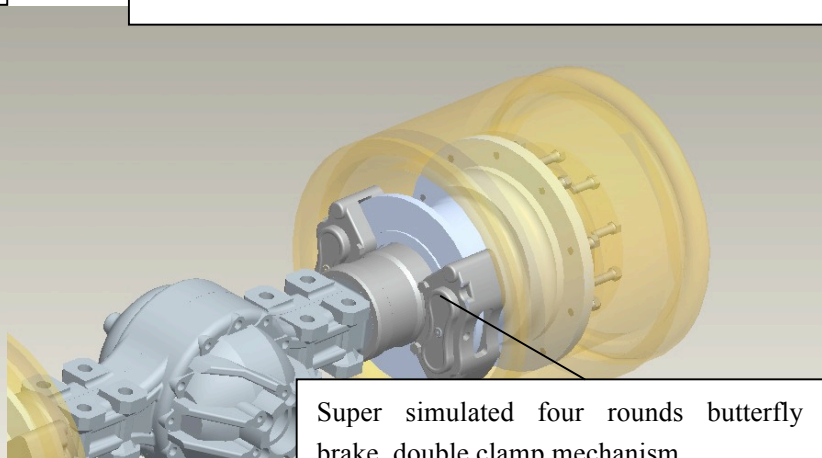
Rear axle swinging bridge design ± 13 degrees, to ensure good tire grip.



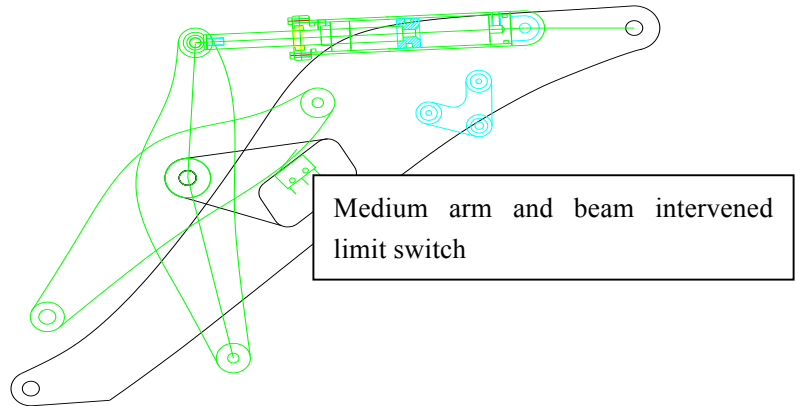
29.5-25L-5 deep pattern for engineering machinery tire design



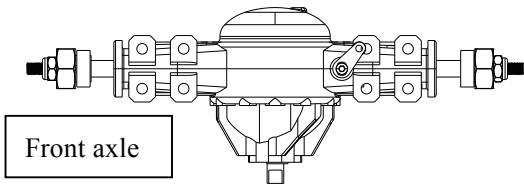
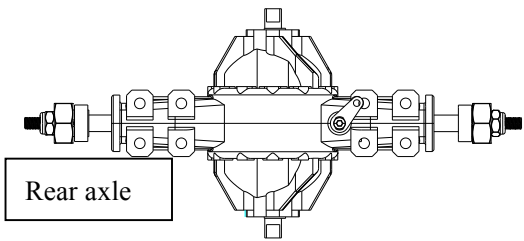
Round edge retarding mechanism



Super simulated four rounds butterfly brake, double clamp mechanism



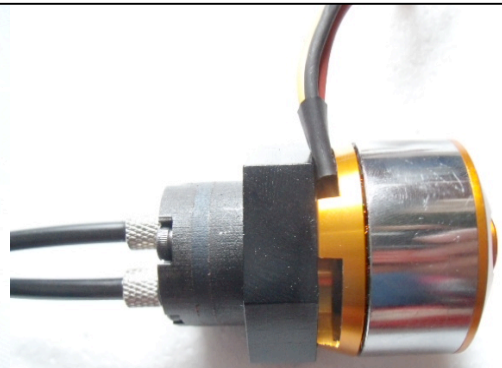
Gearbox: using static point model latest planetary gearbox, appearance simulated. Compact structure, simulation zip type shift. The torque is large, can shift in March. The reduction ratio



Full alloy drive axle: single reduced and simulated bridge design, can remote control differential lock .

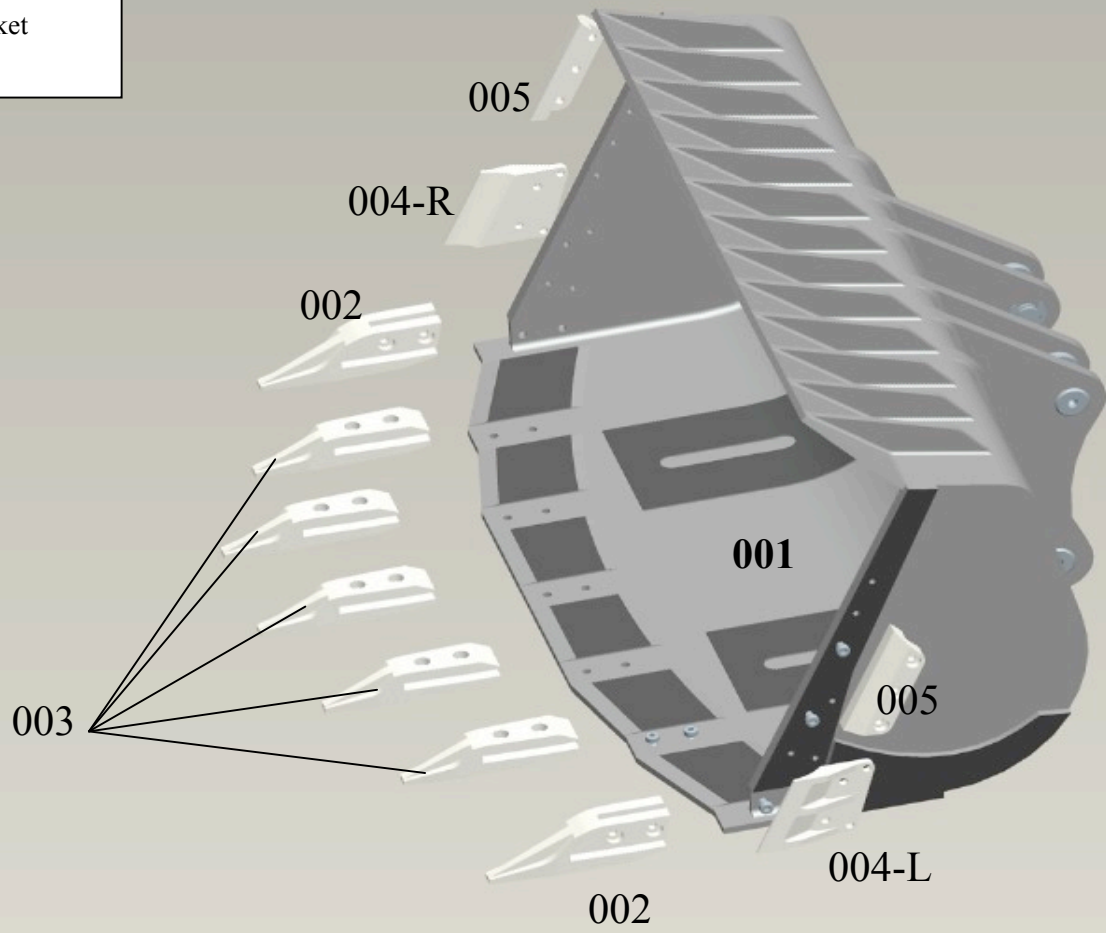


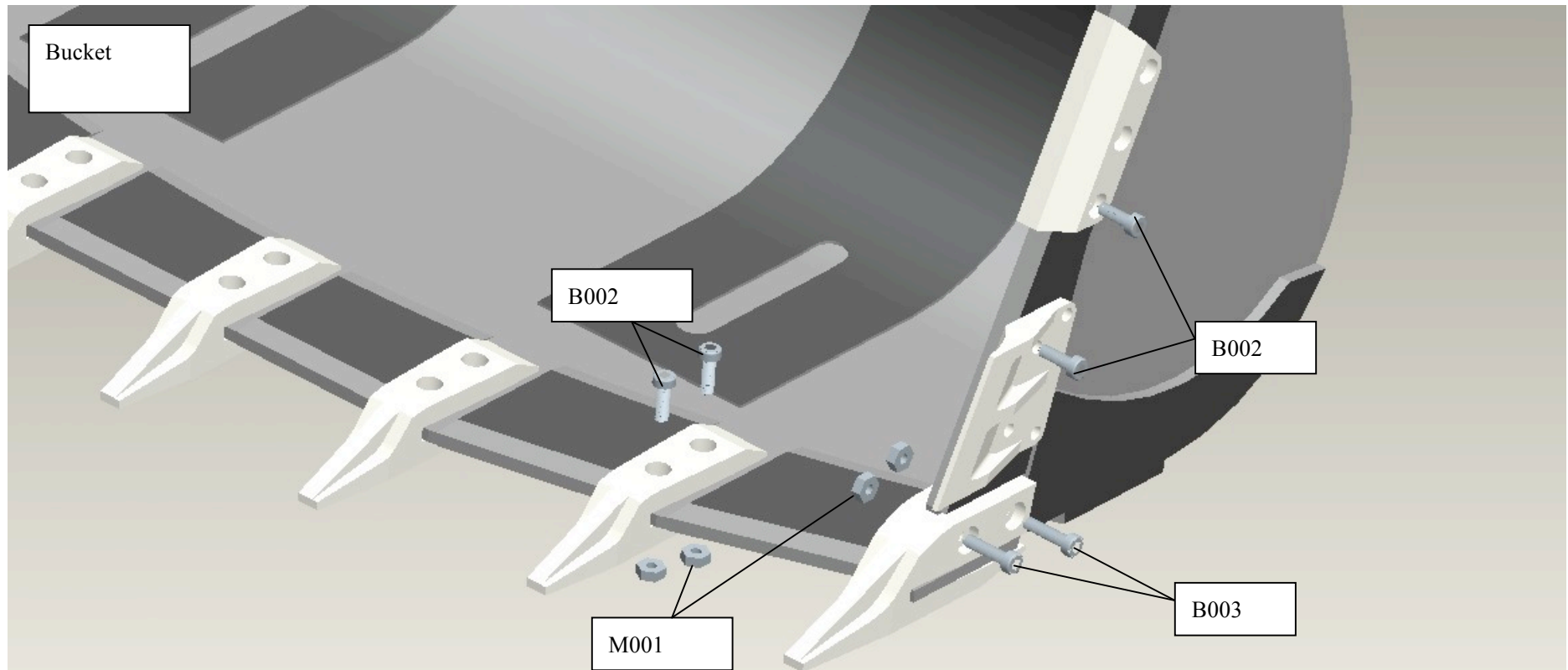
Shaft: equipped with static point model early V gradually opening Angle shaft, spline type structure, simulated and big torque

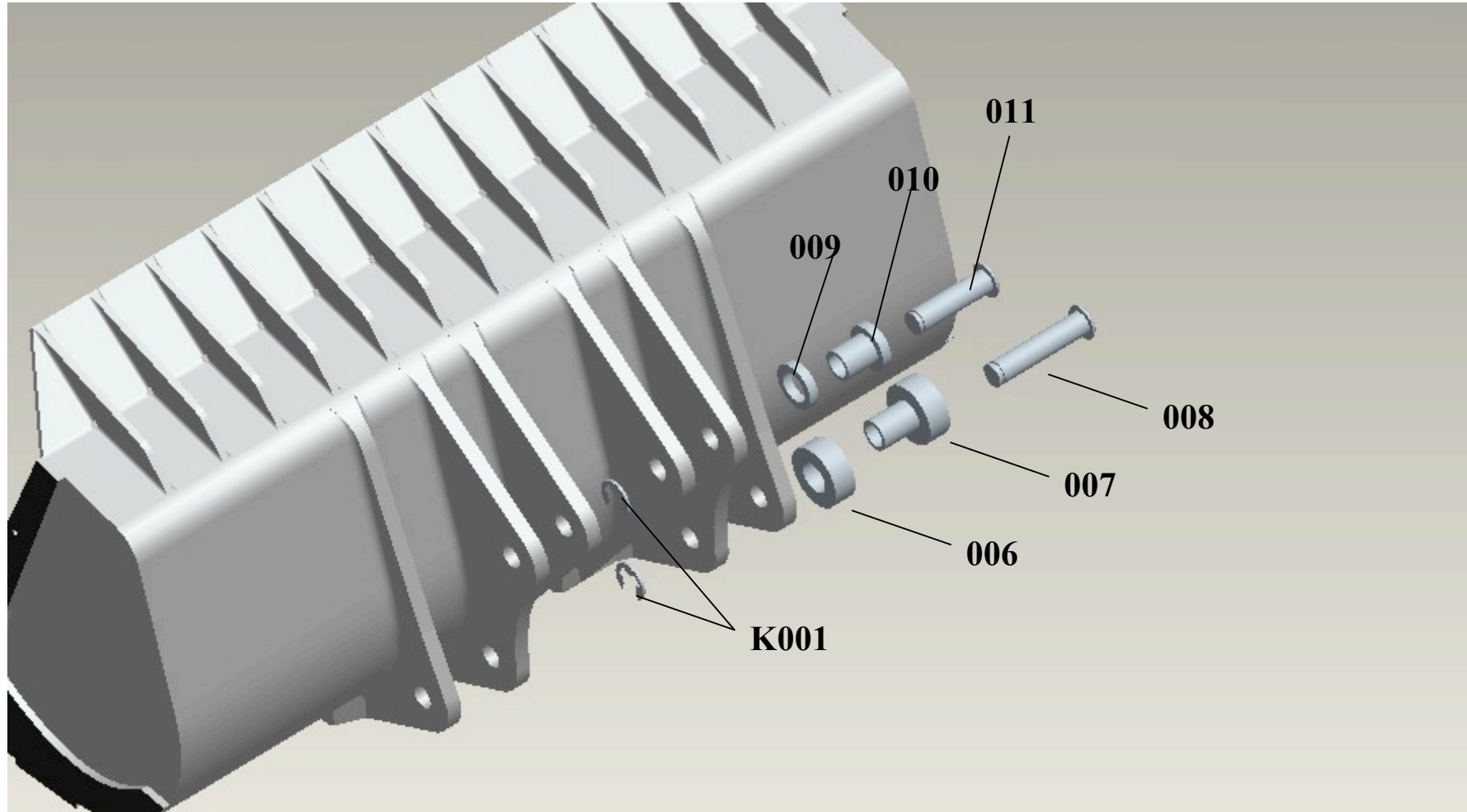


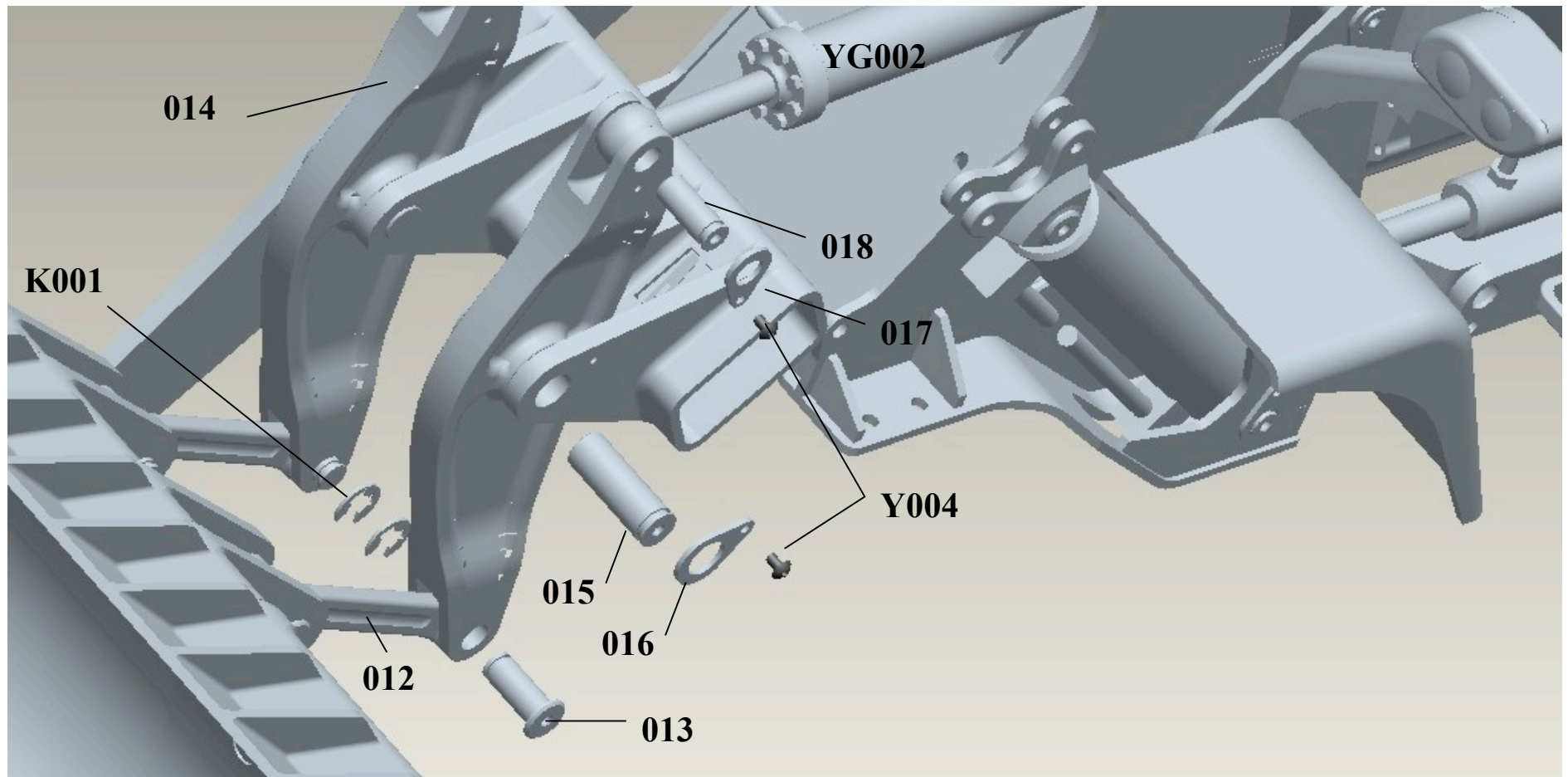
Oil pump: 2814 brushless motor drive, rated pressure 3.5-5MPA, flow rate: 0.42 L/MIN. Small size with high efficiency. Driven by a brushless electronic controller 40A.

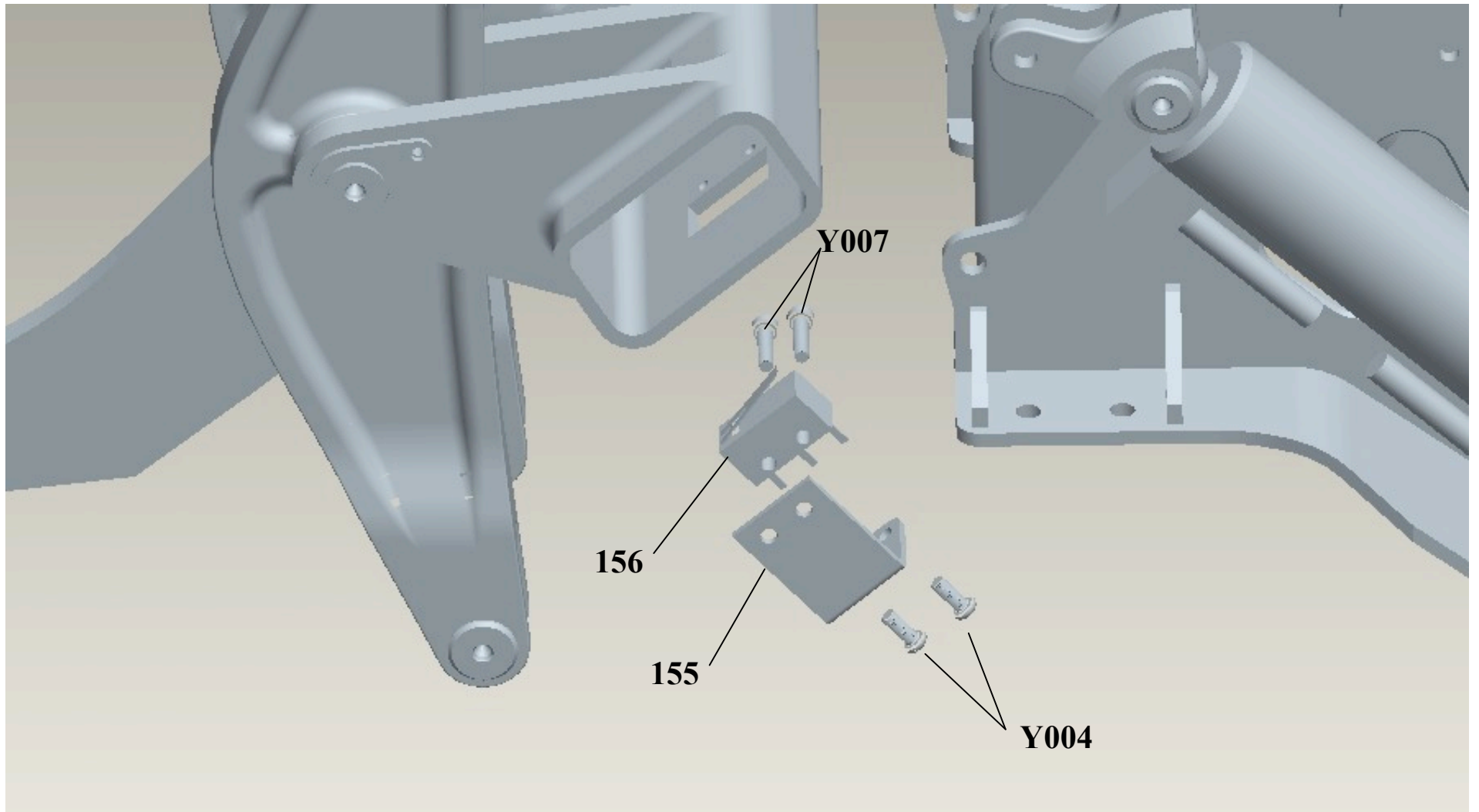
Bucket

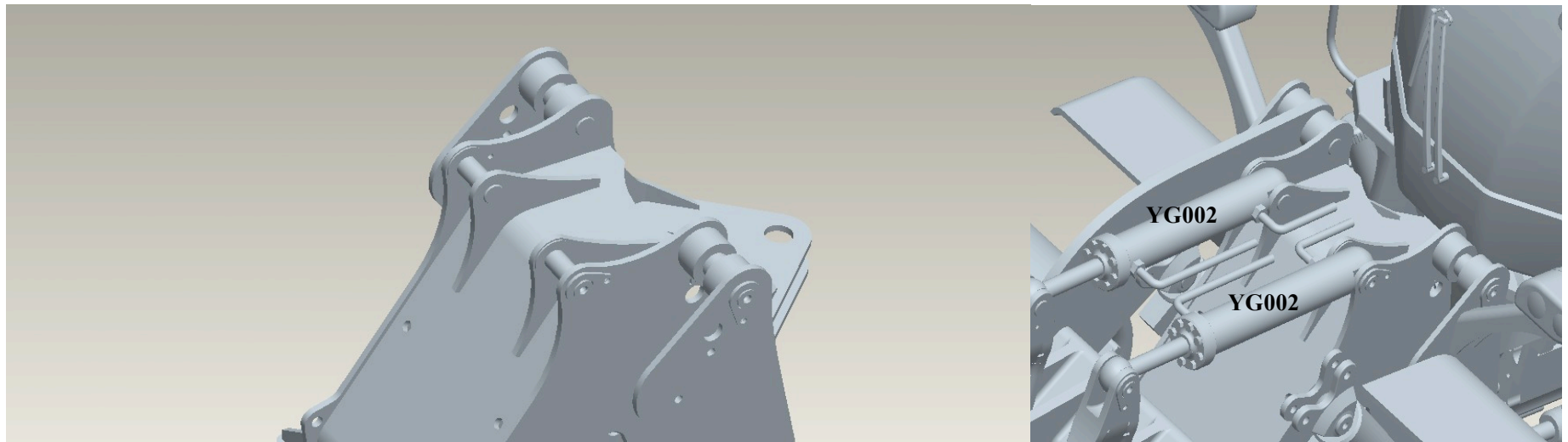
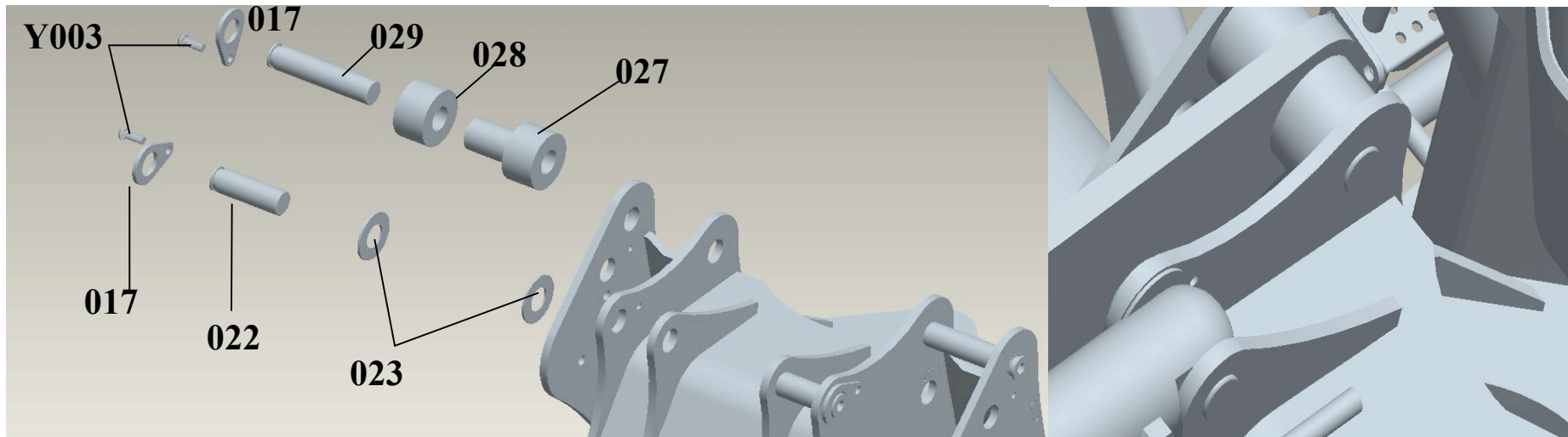


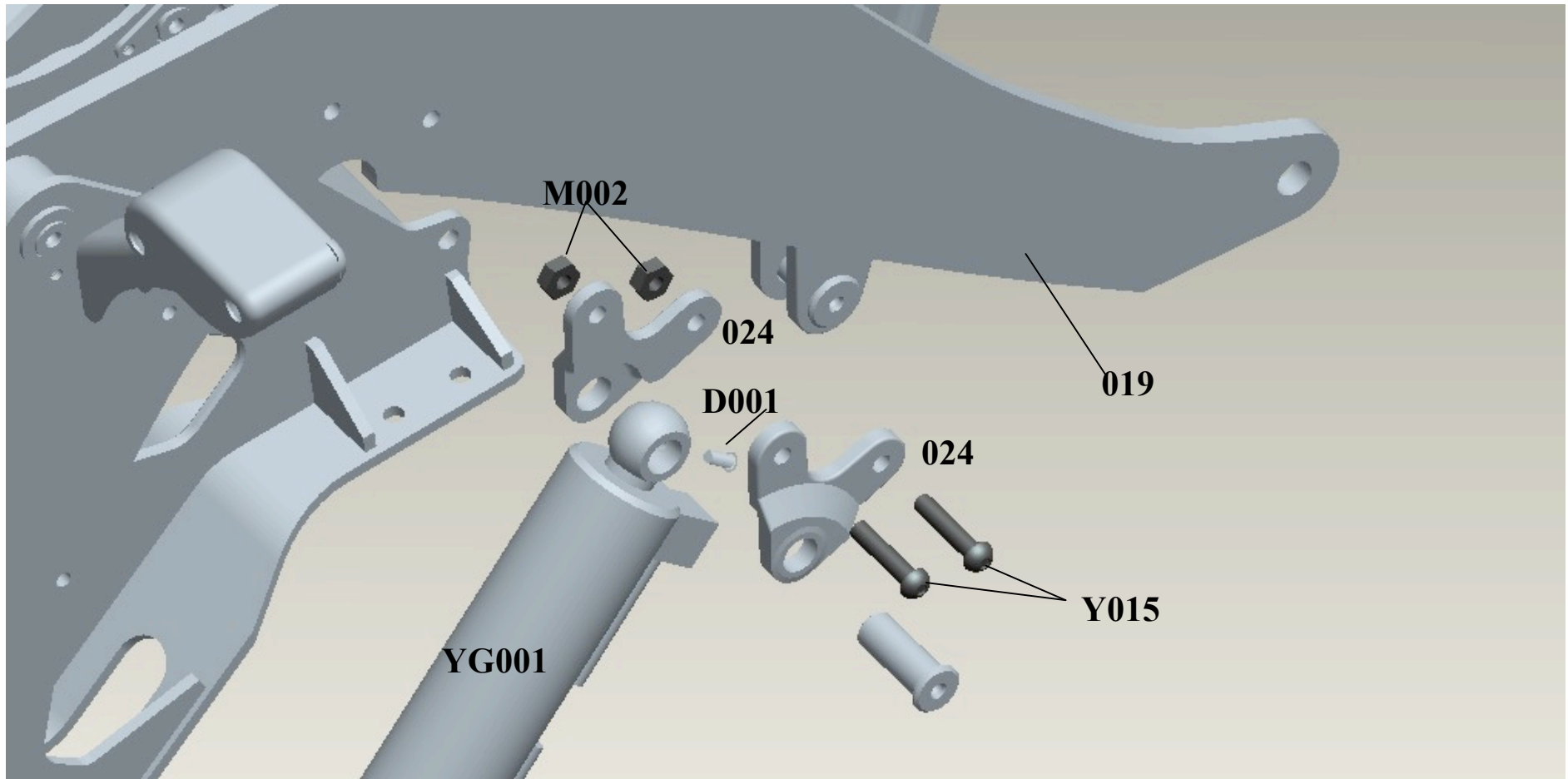


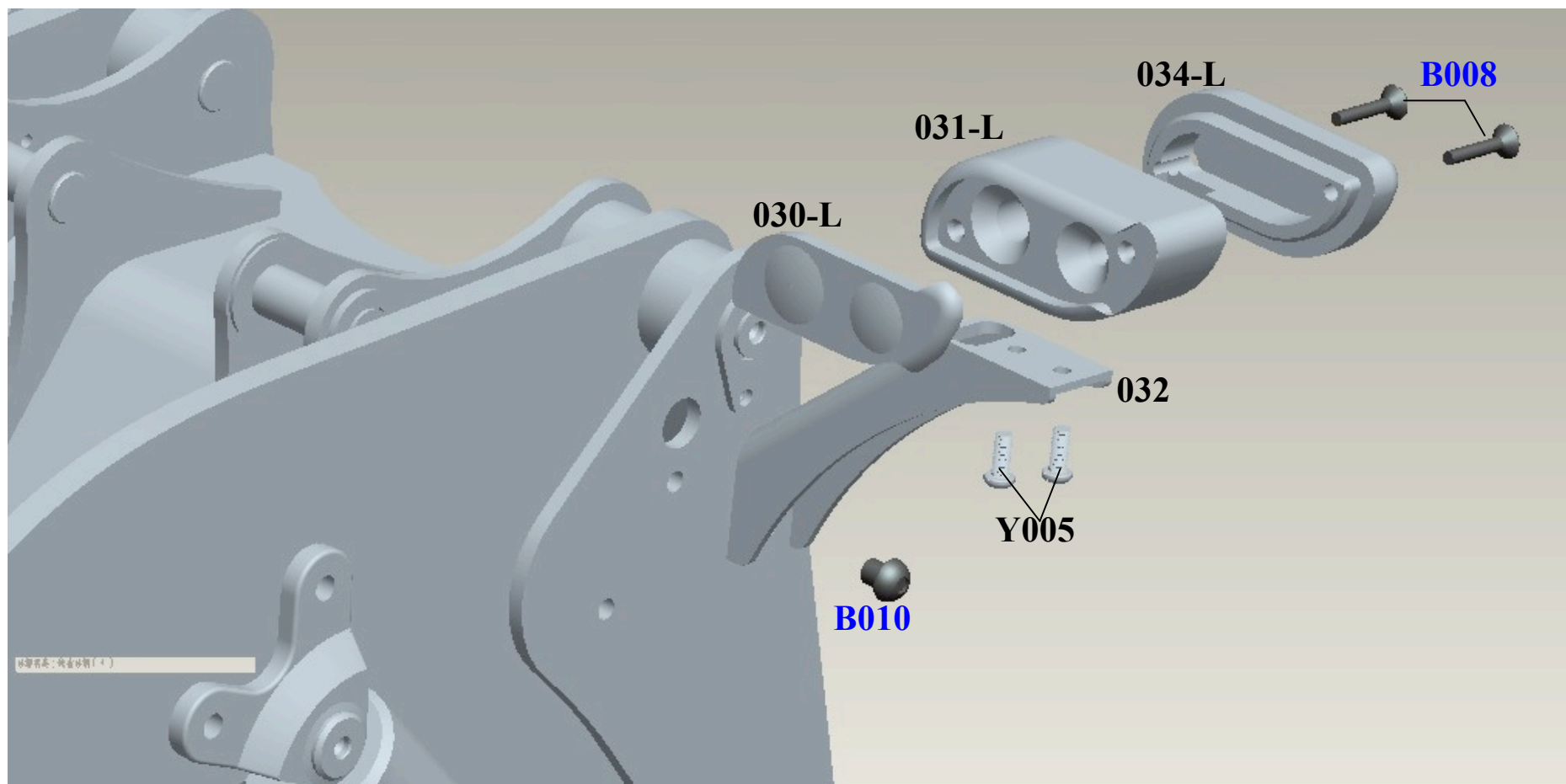


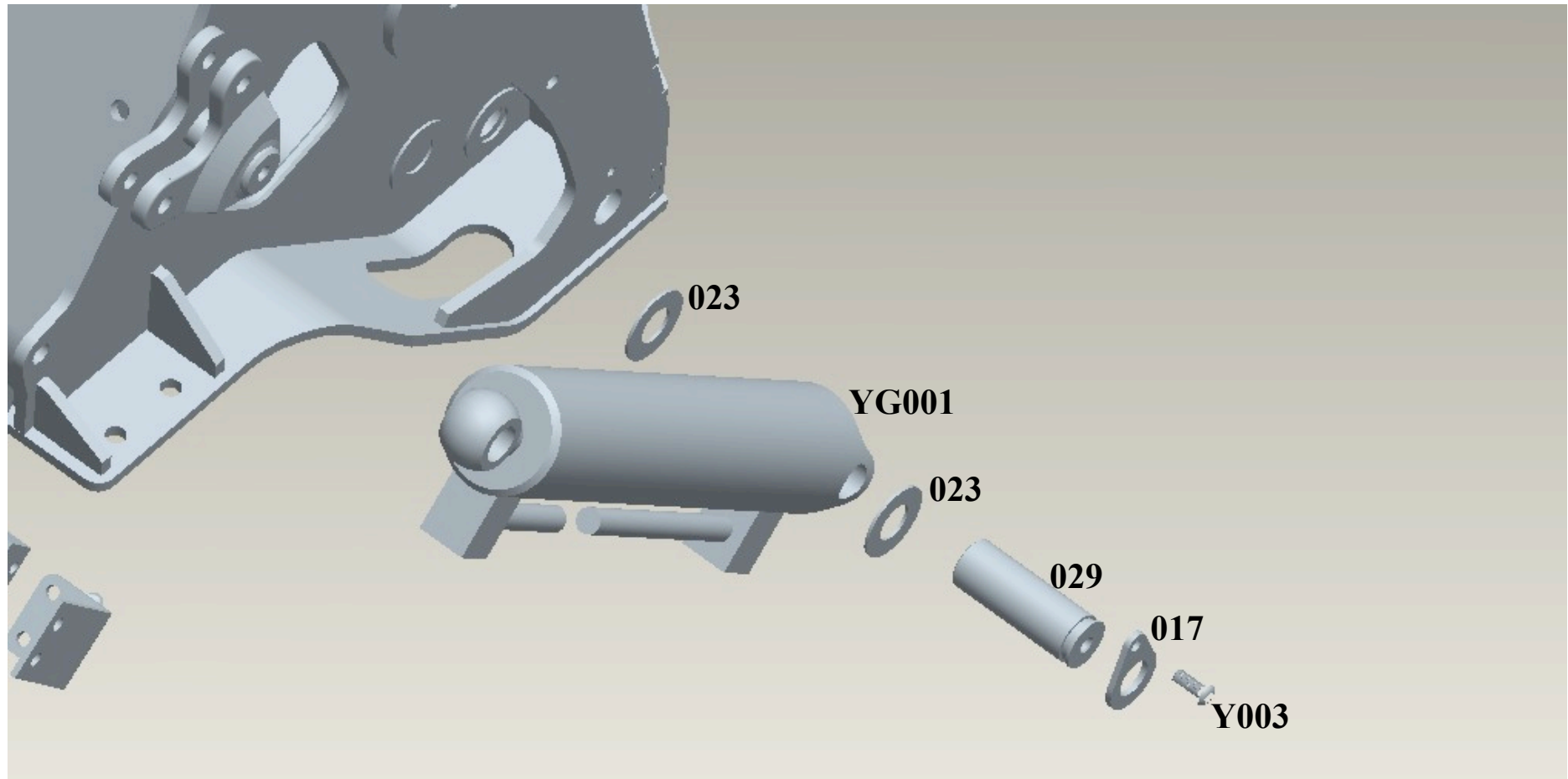


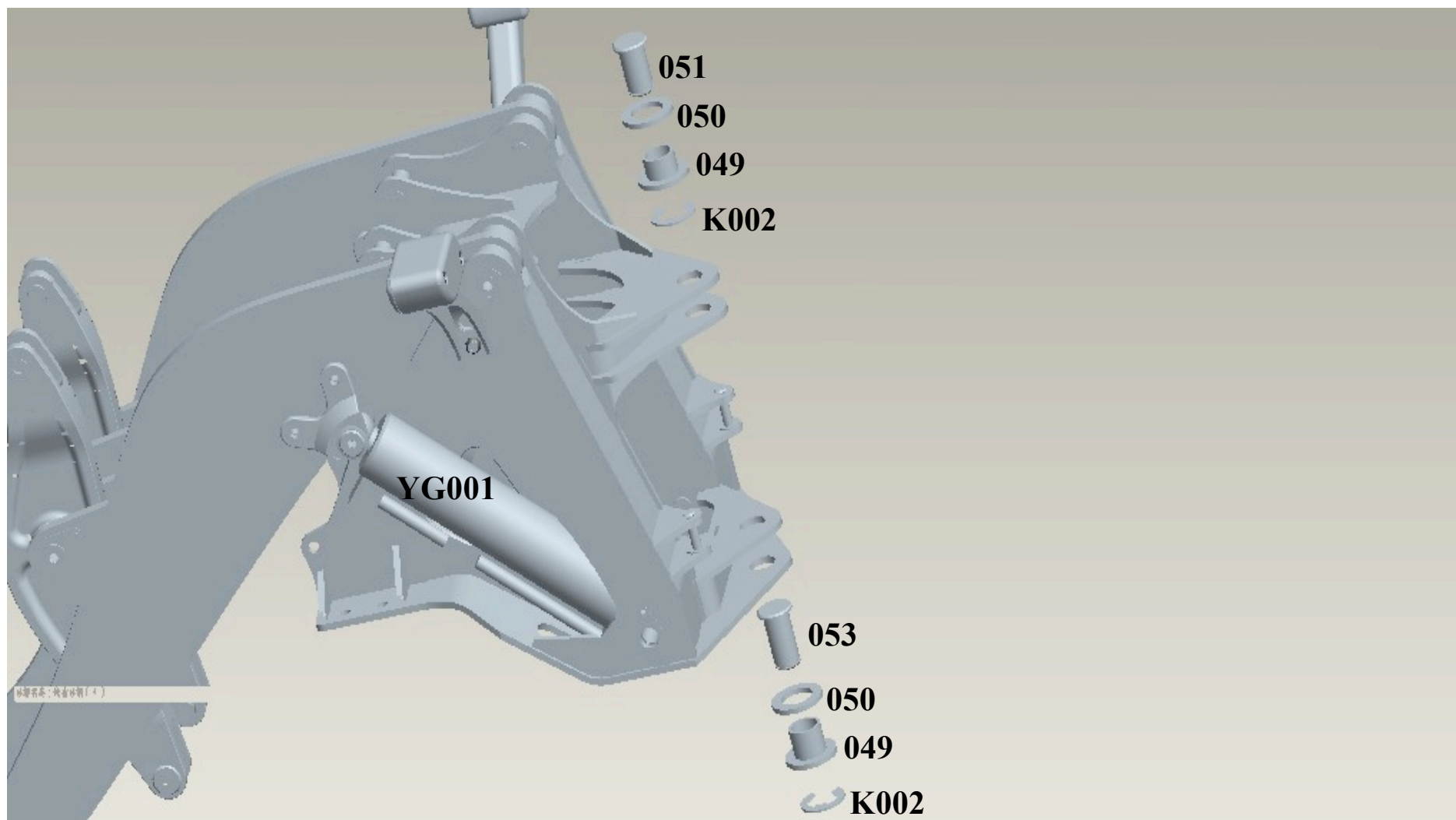


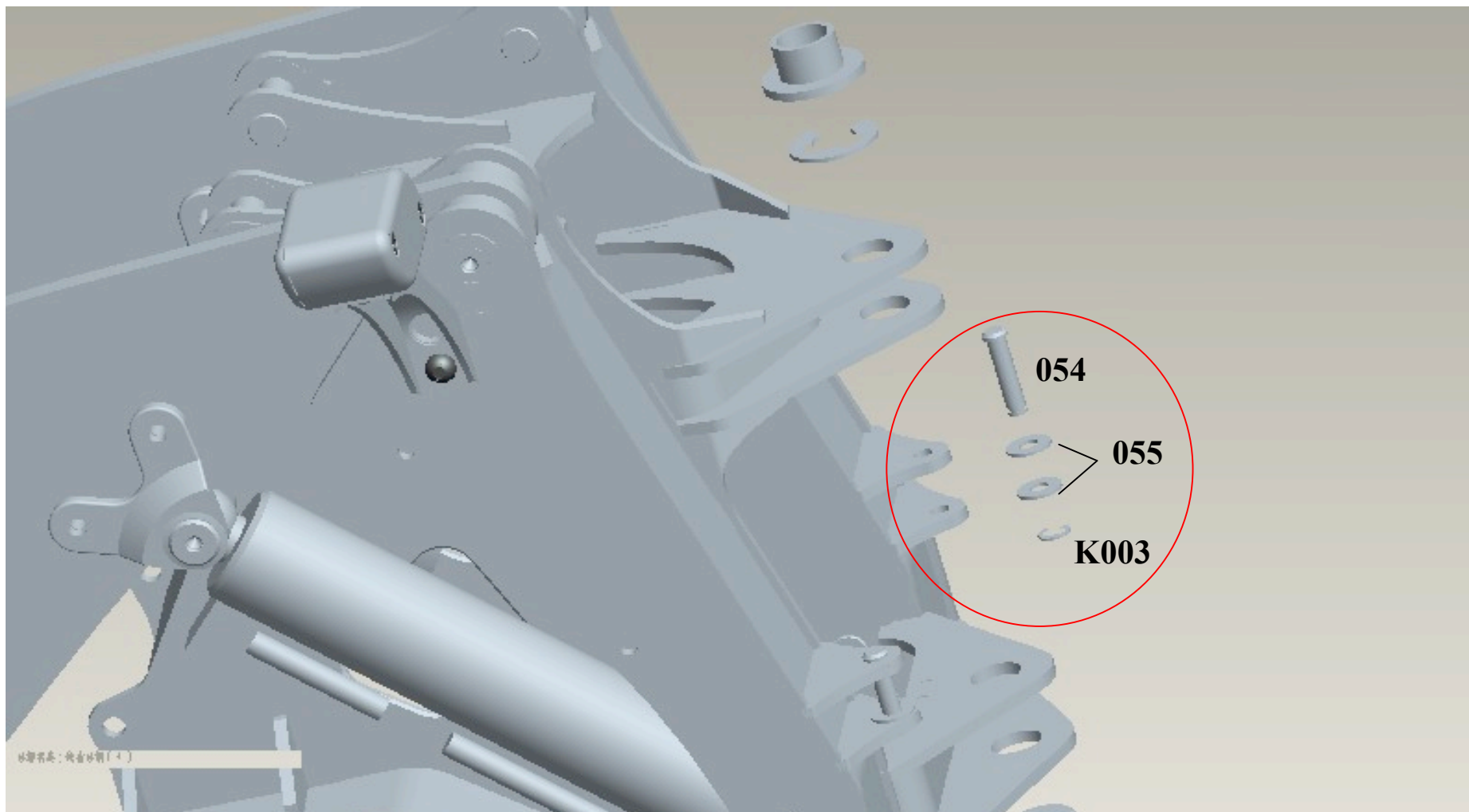


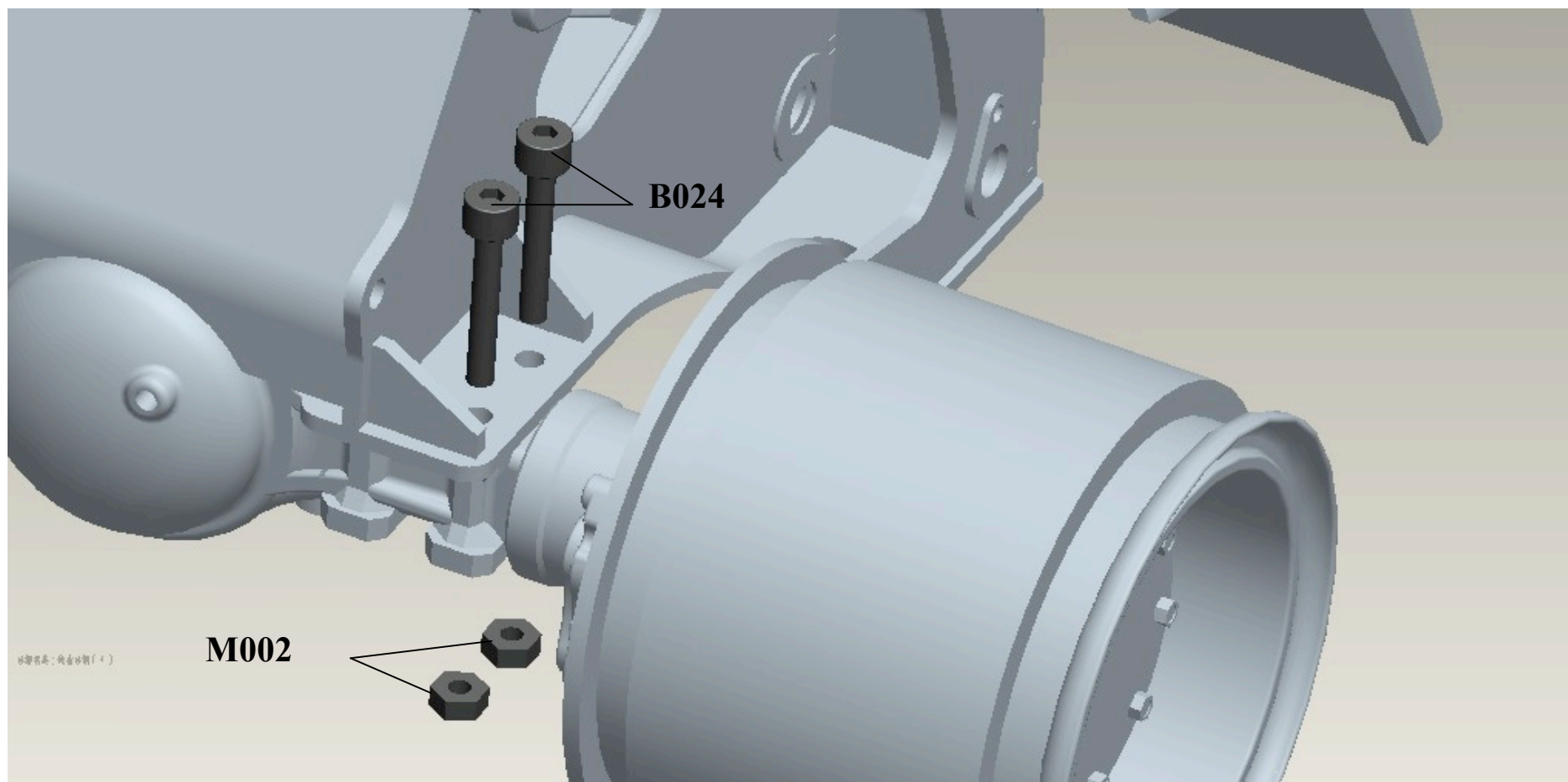


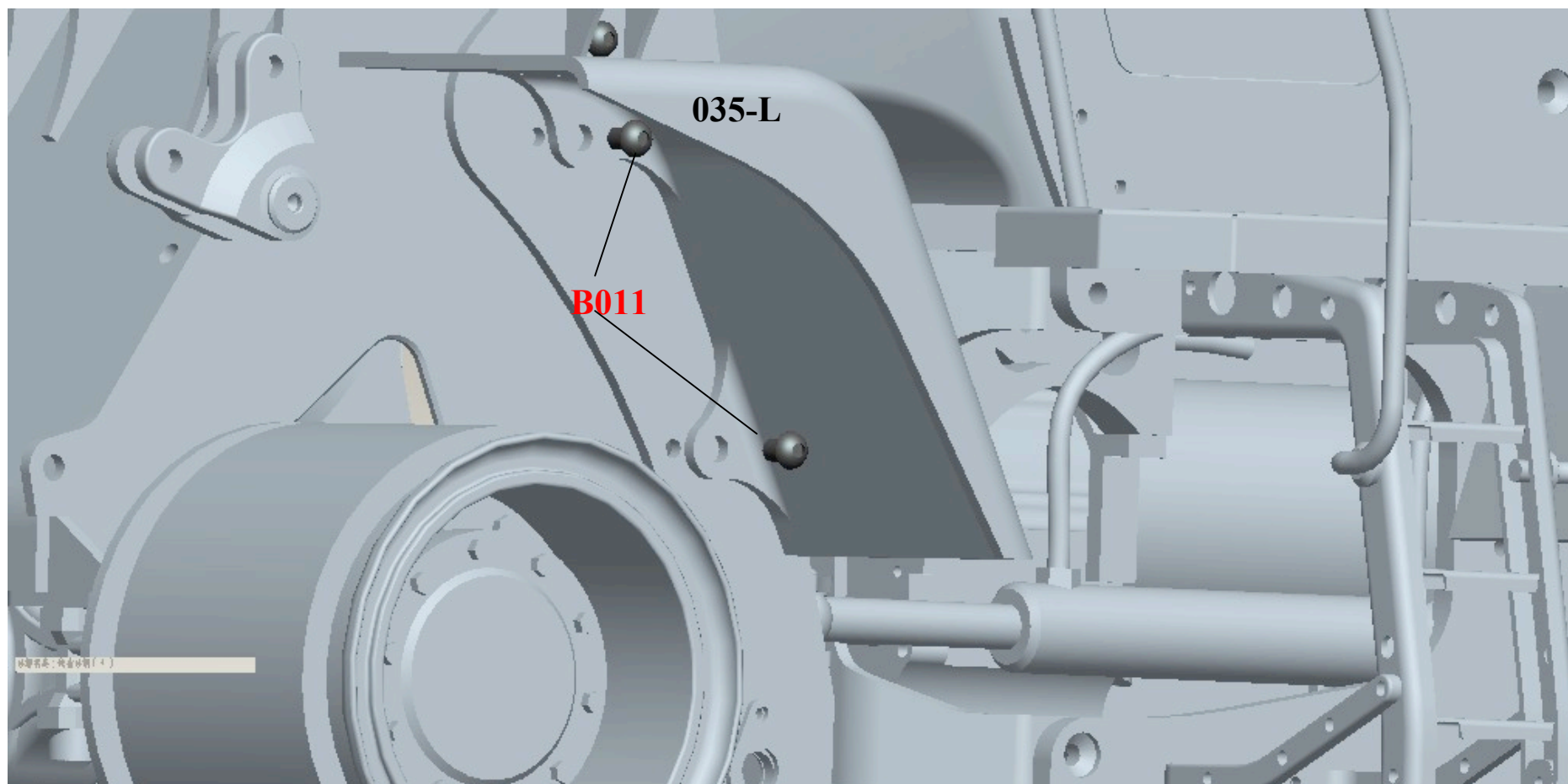


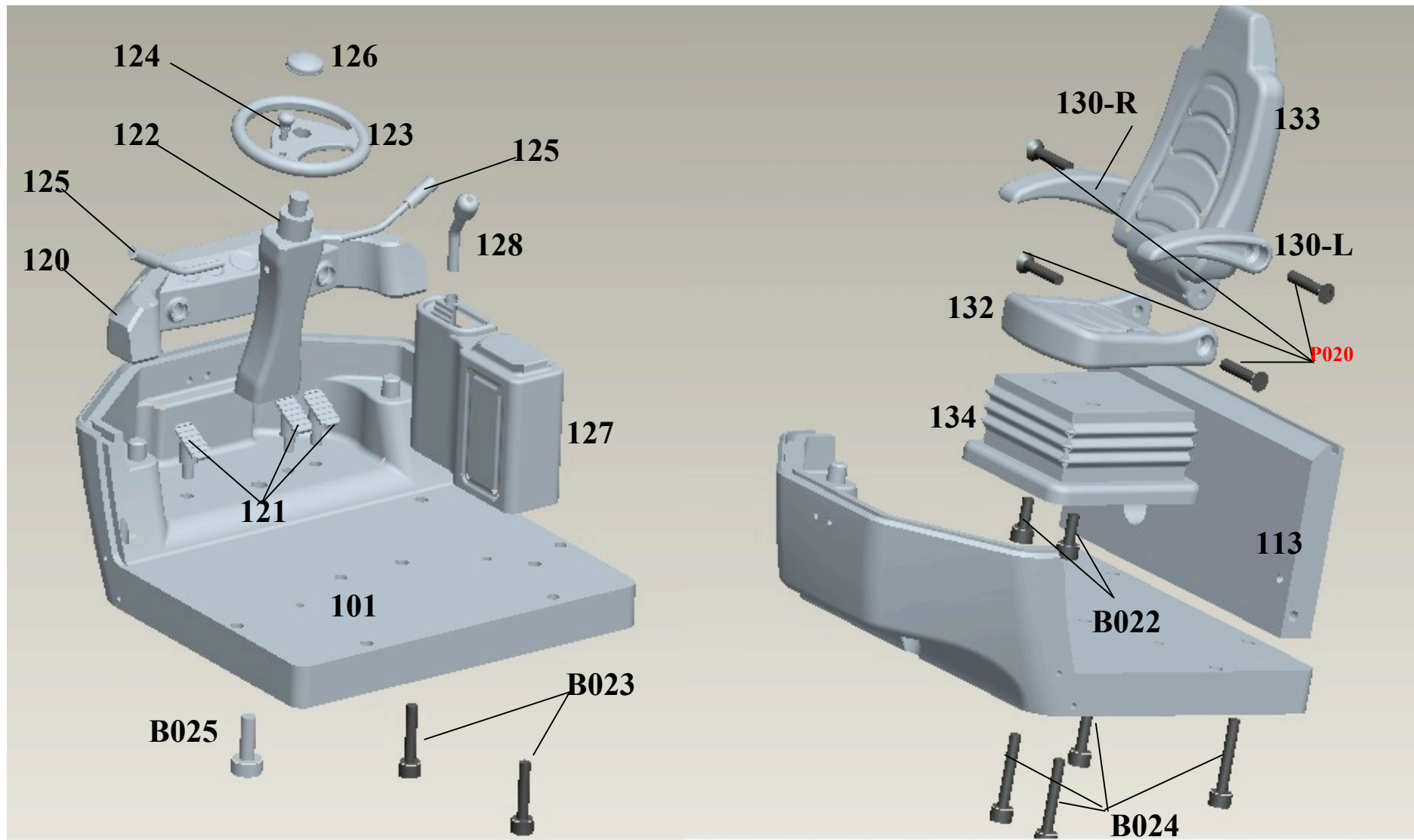


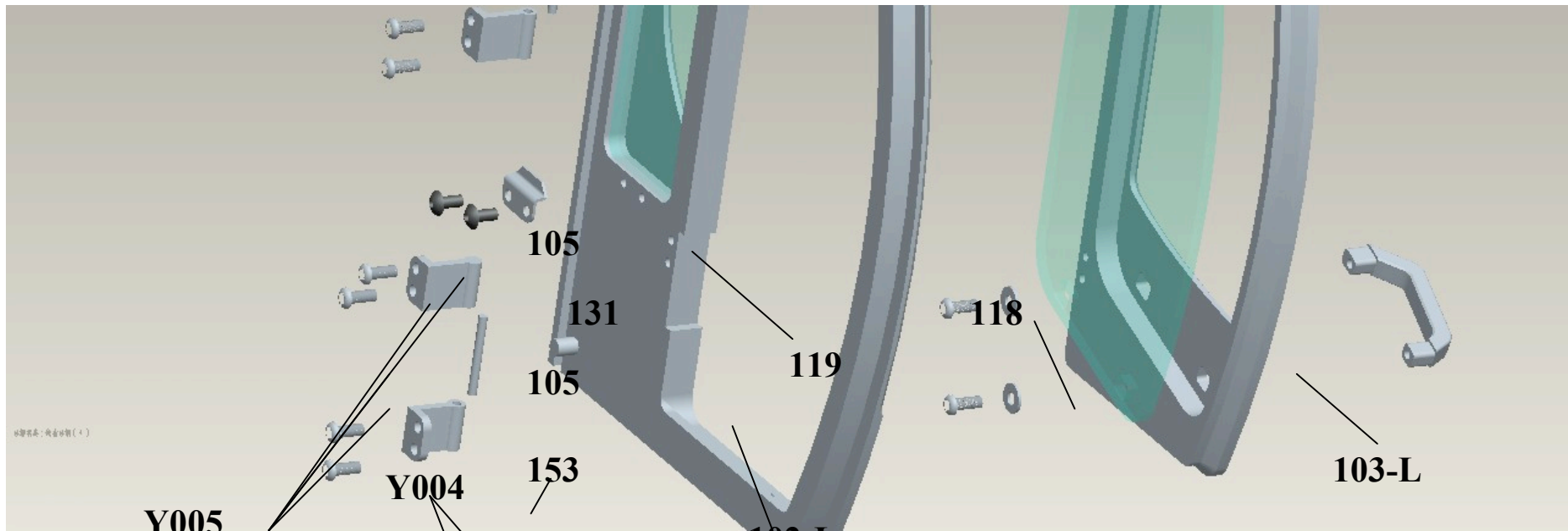












Y005

Y004

105

131

105

153

119

102-L

118

103-L

106

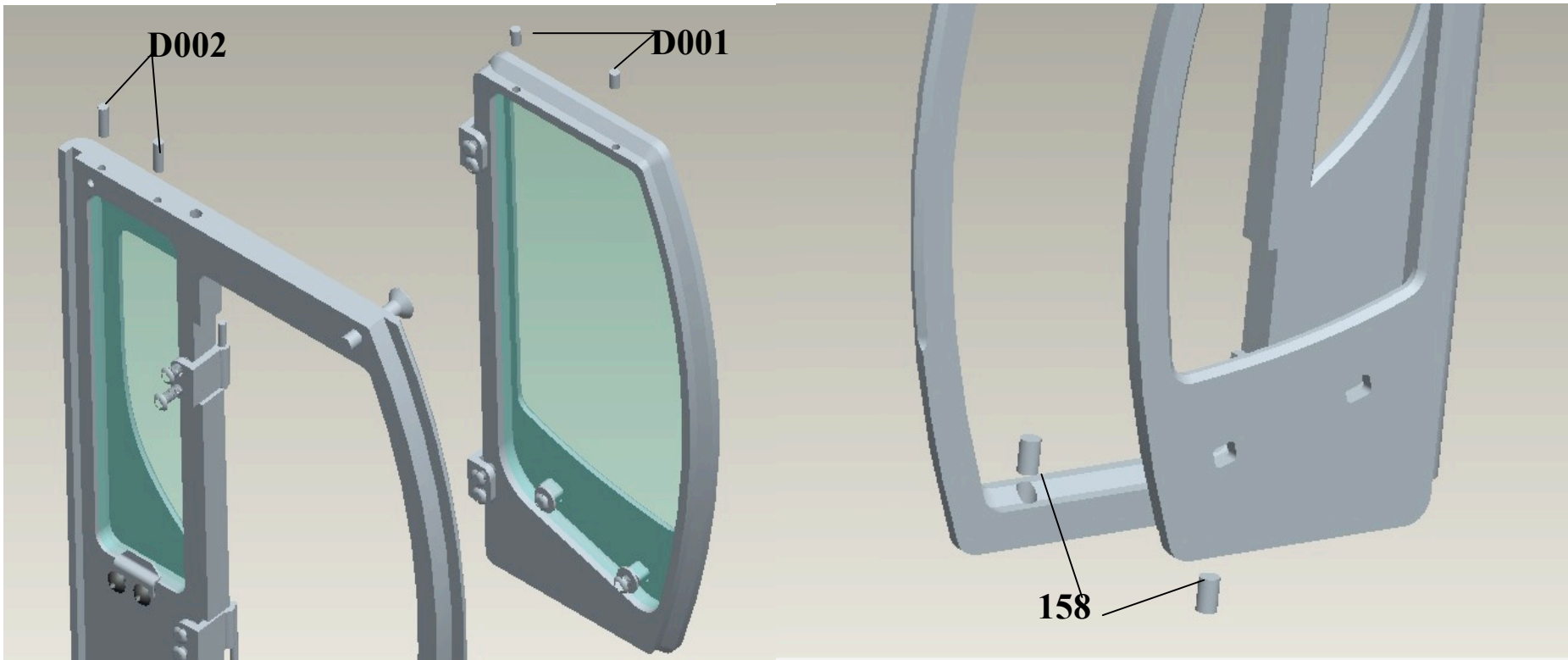
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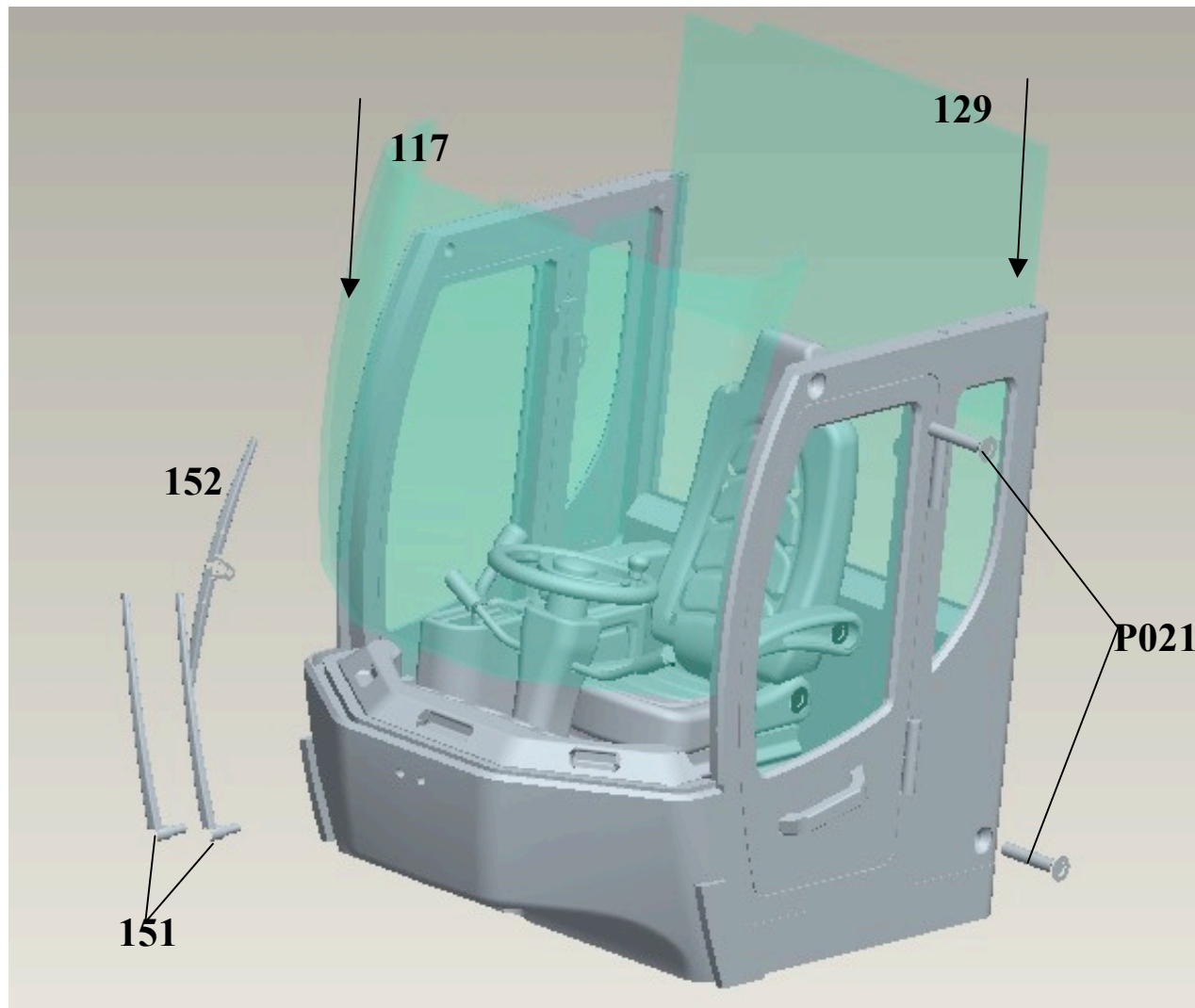
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104

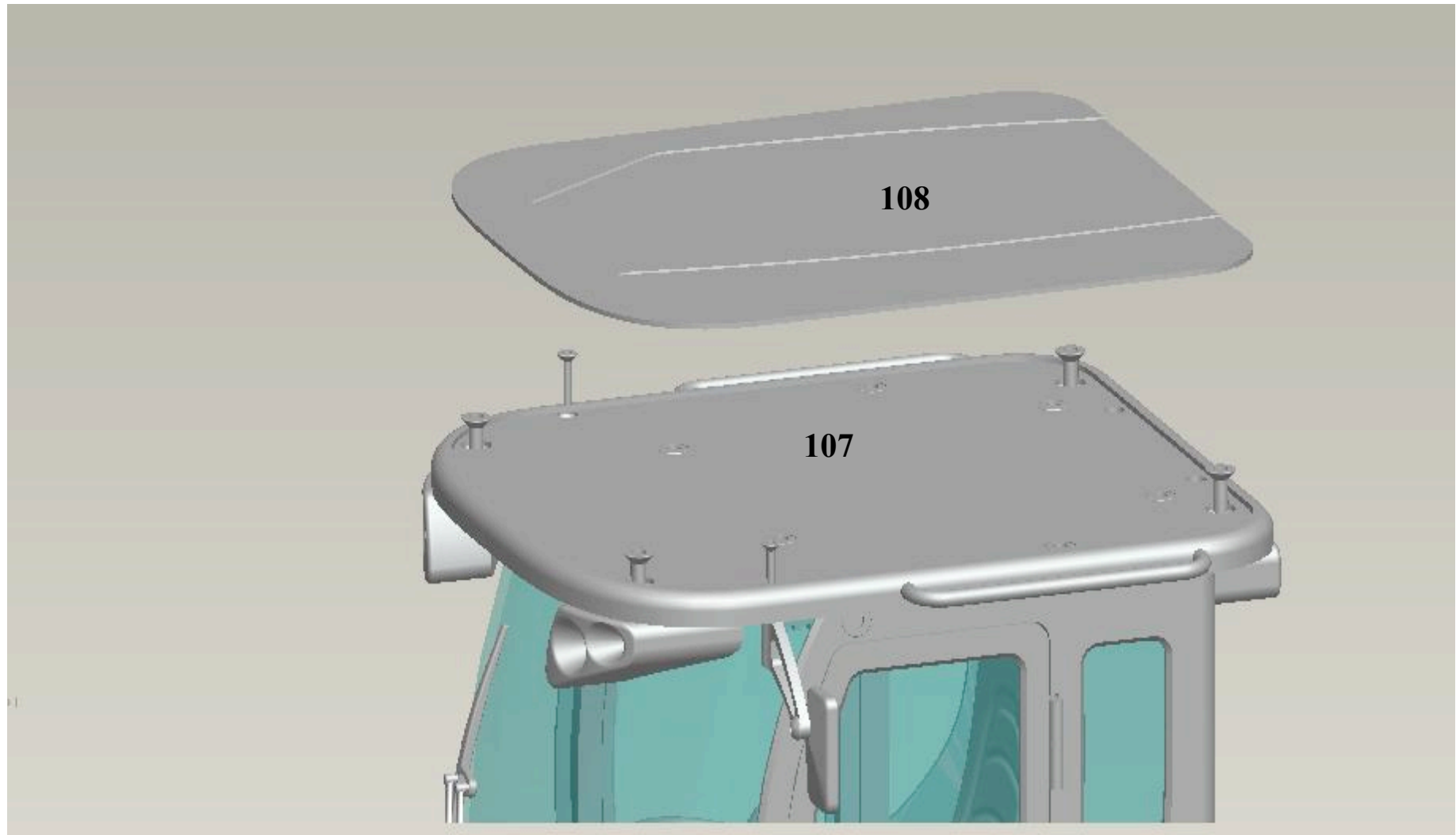
Y004

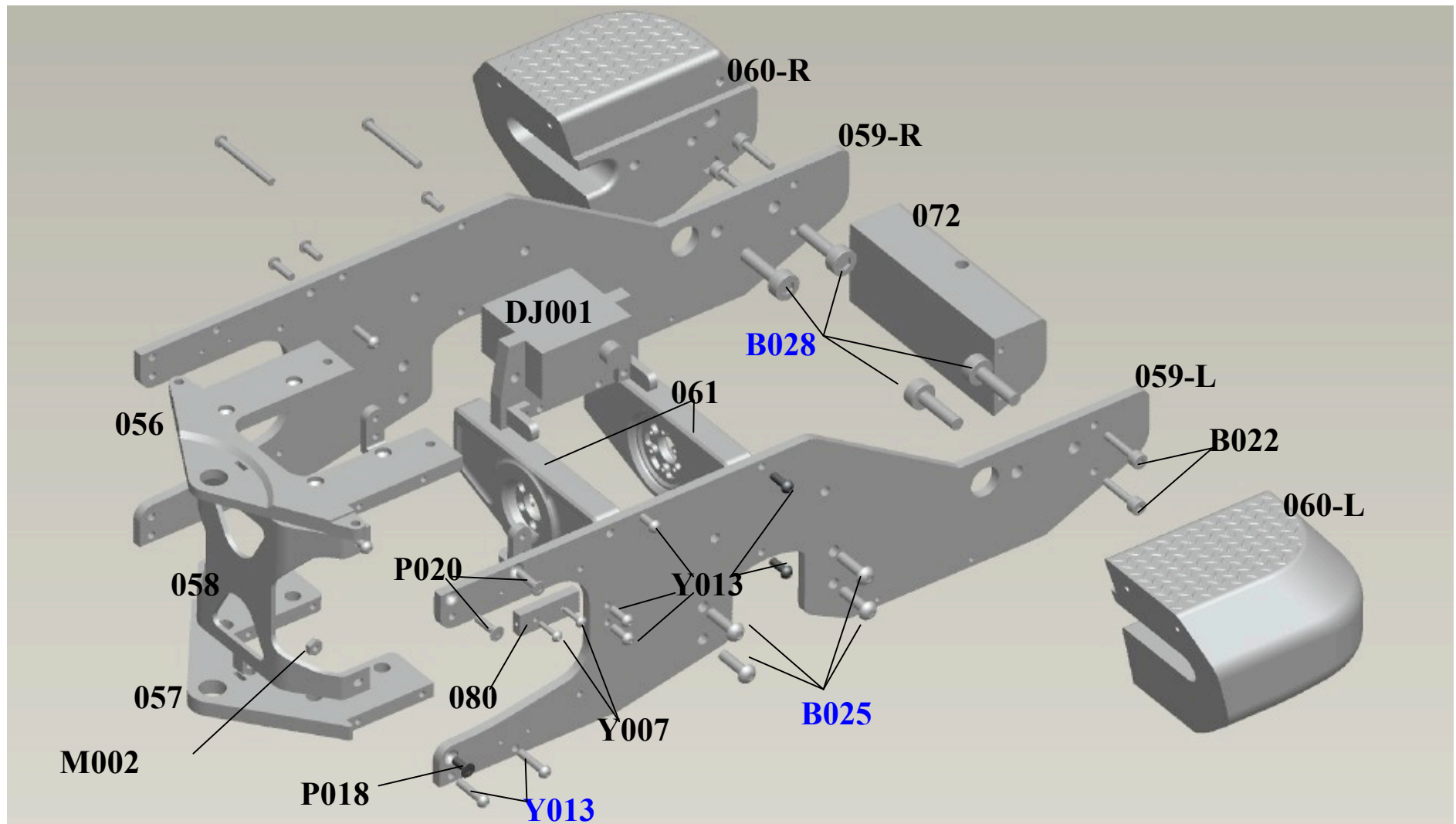
DP001

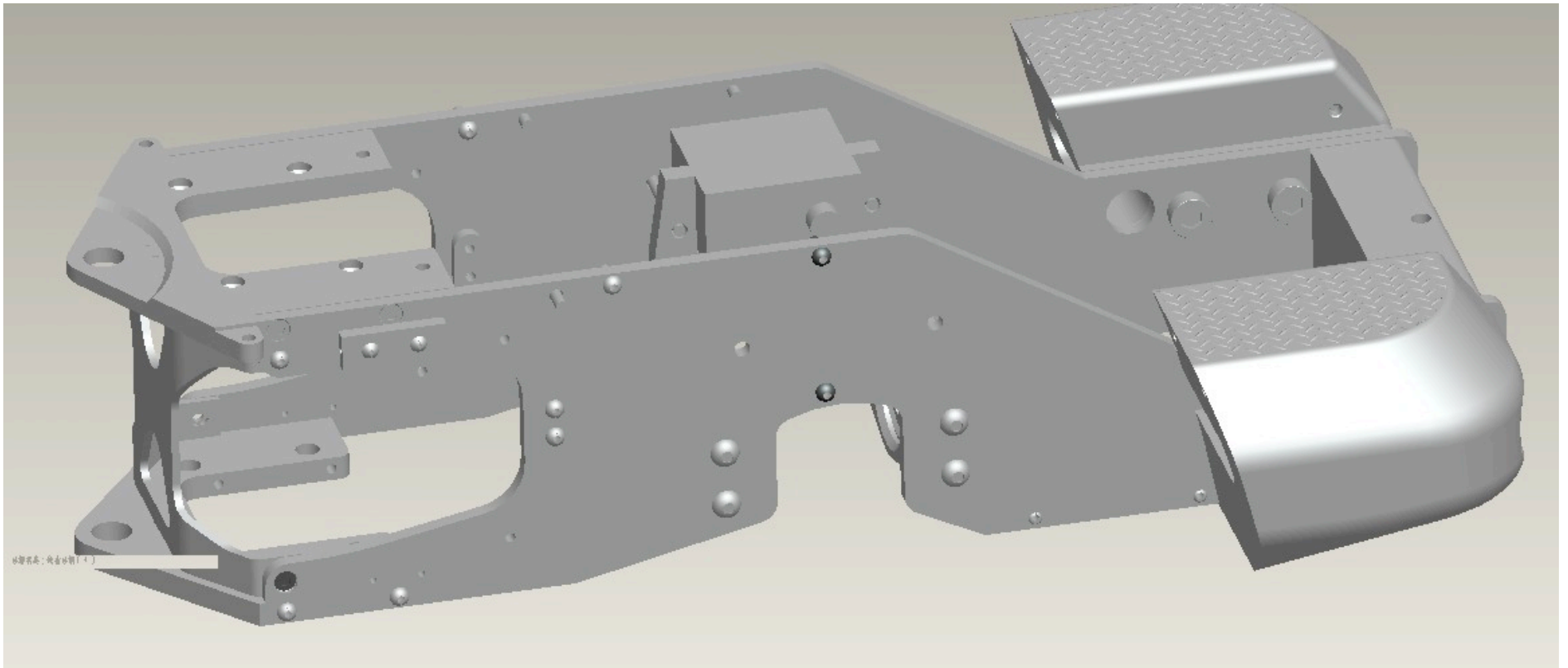


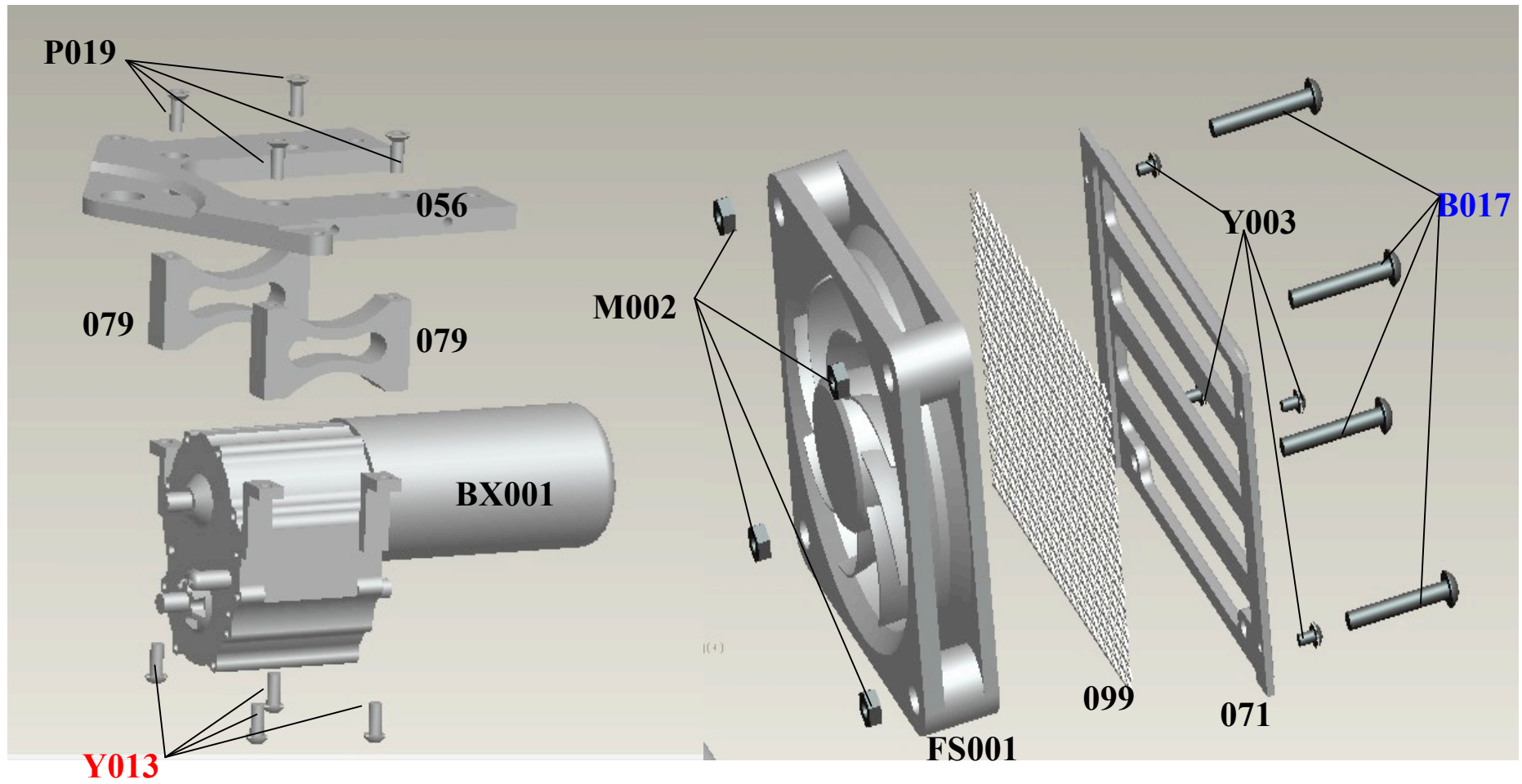


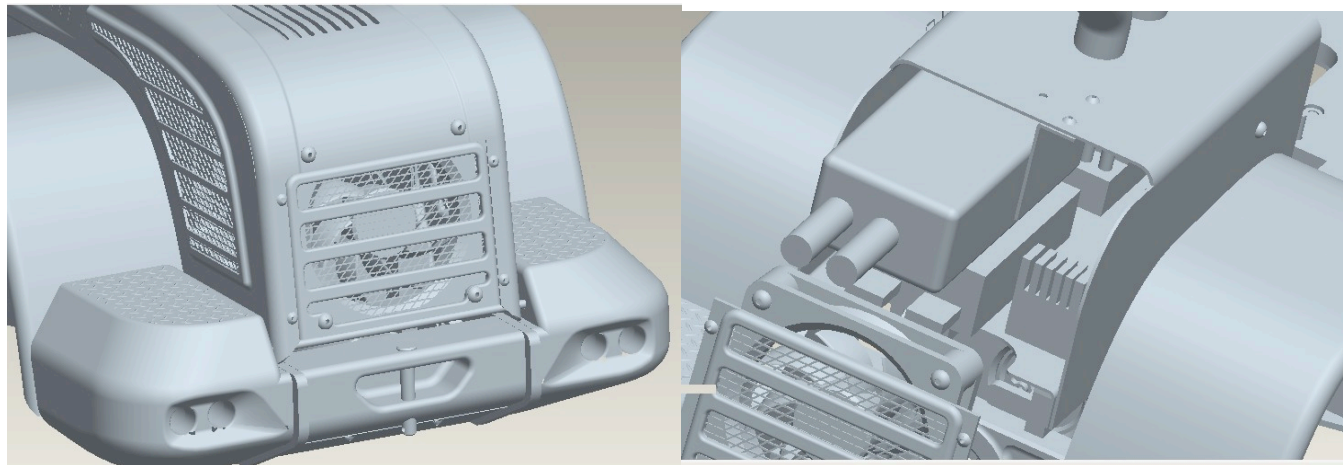
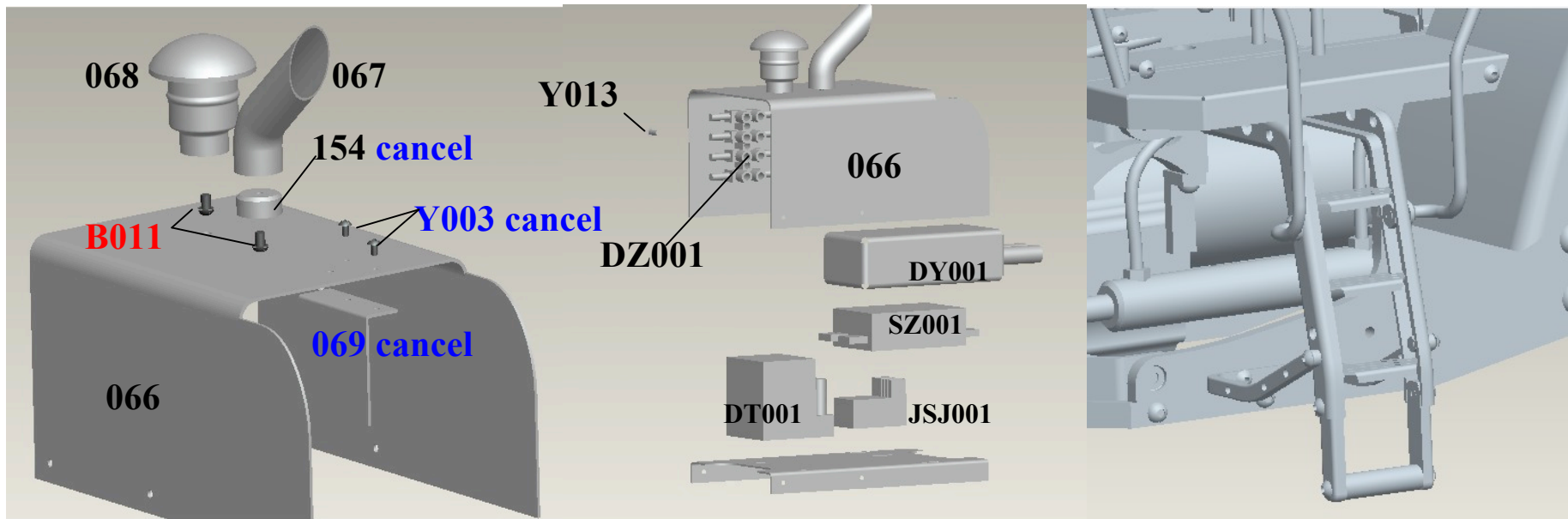
P021 switched to P020

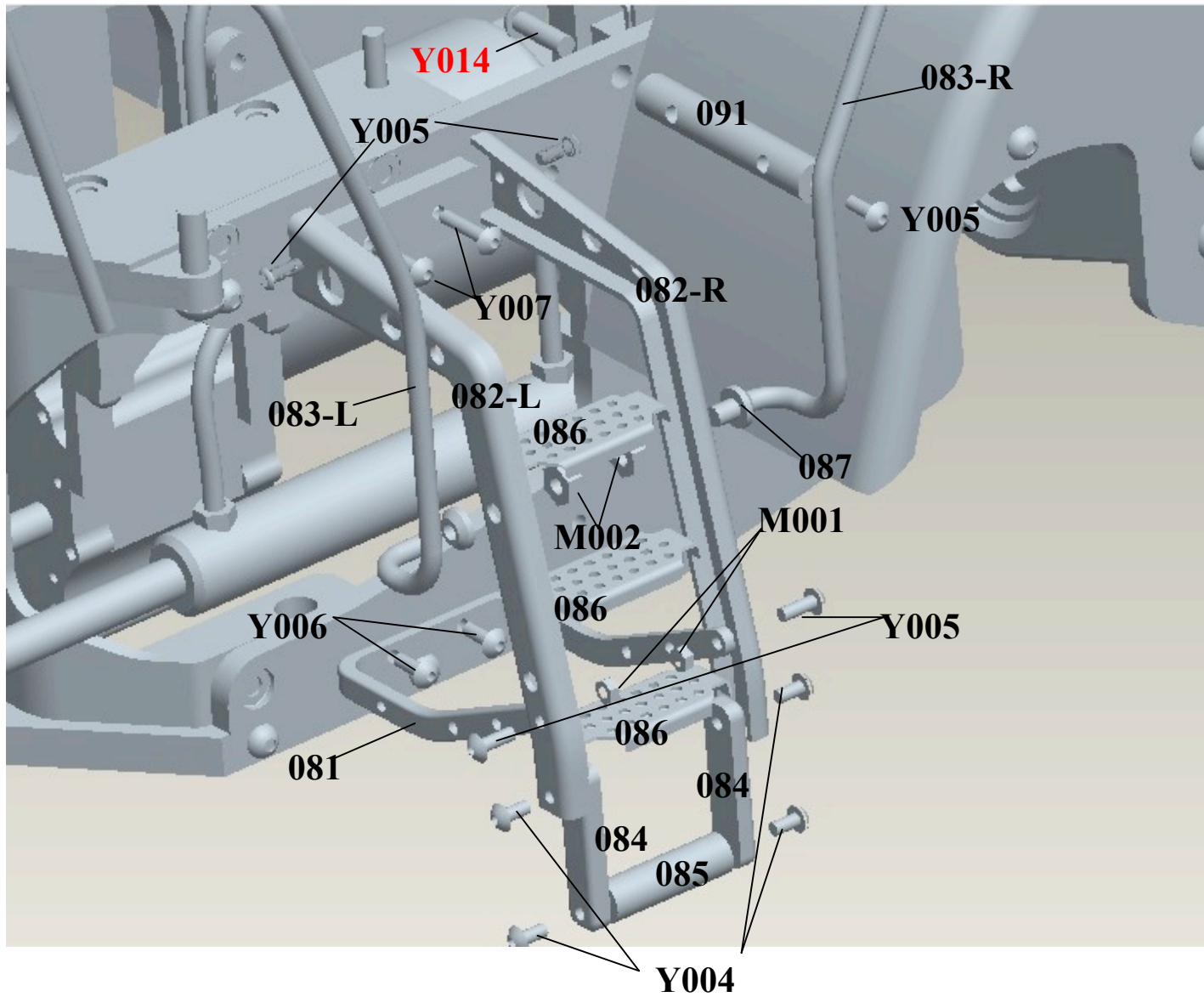


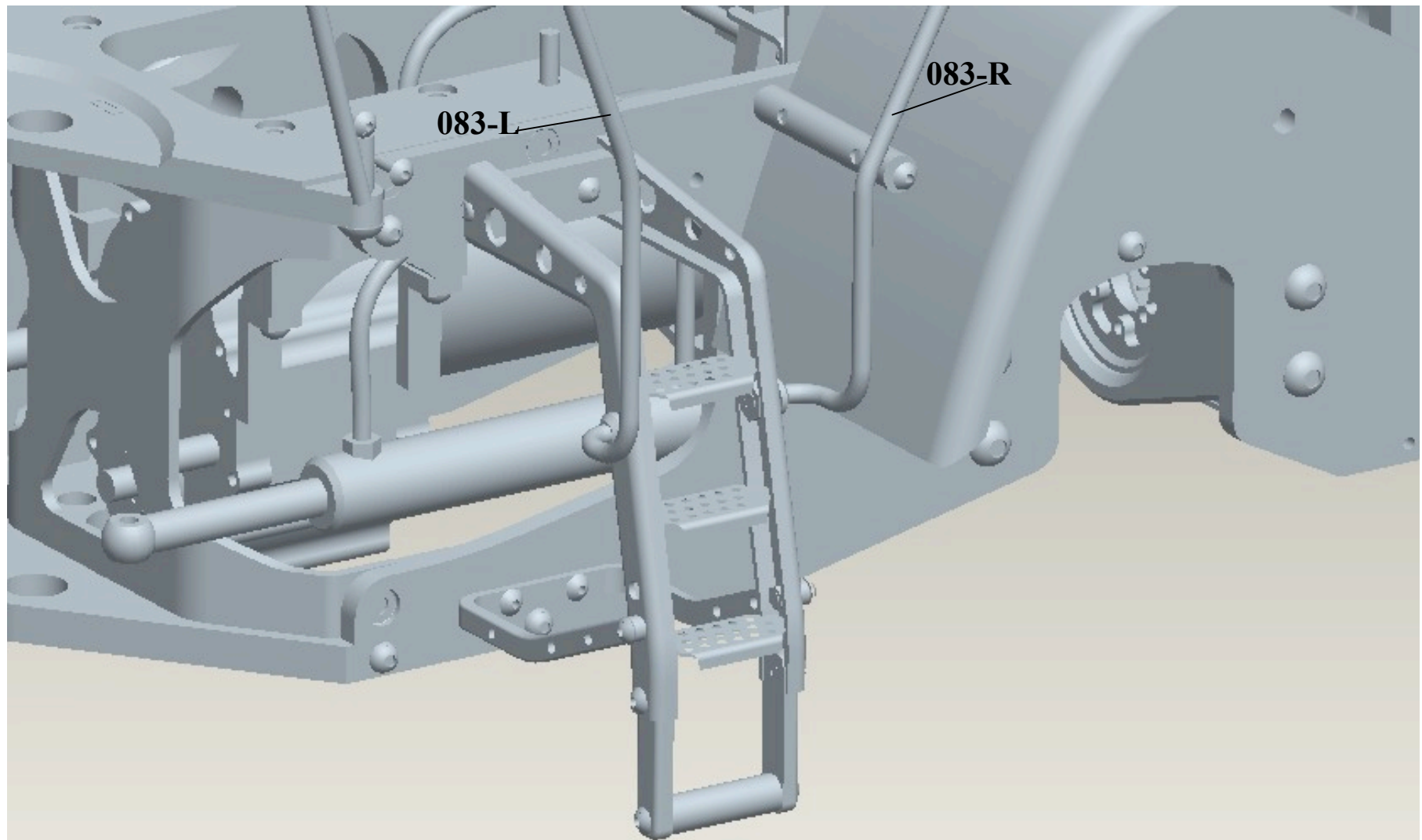


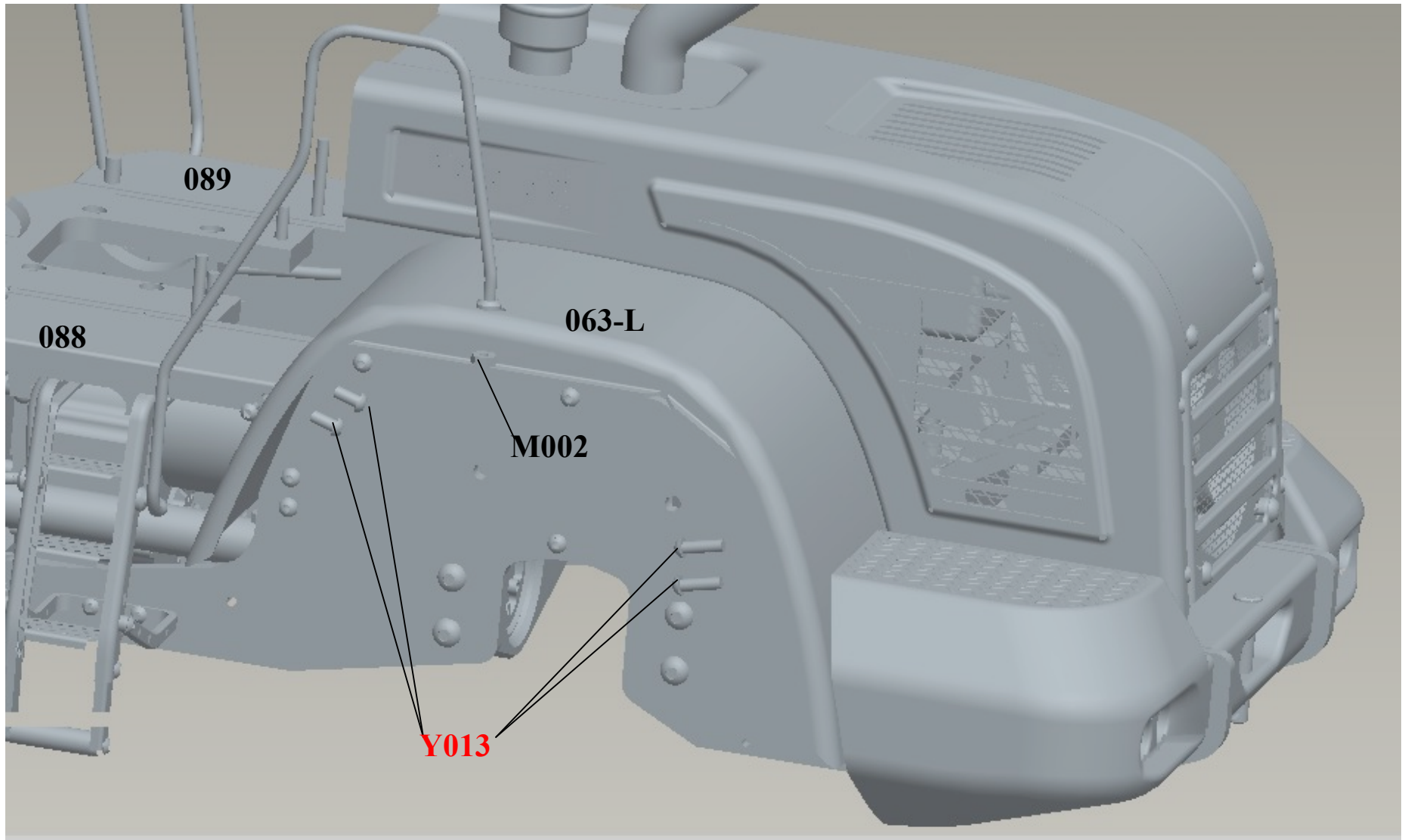


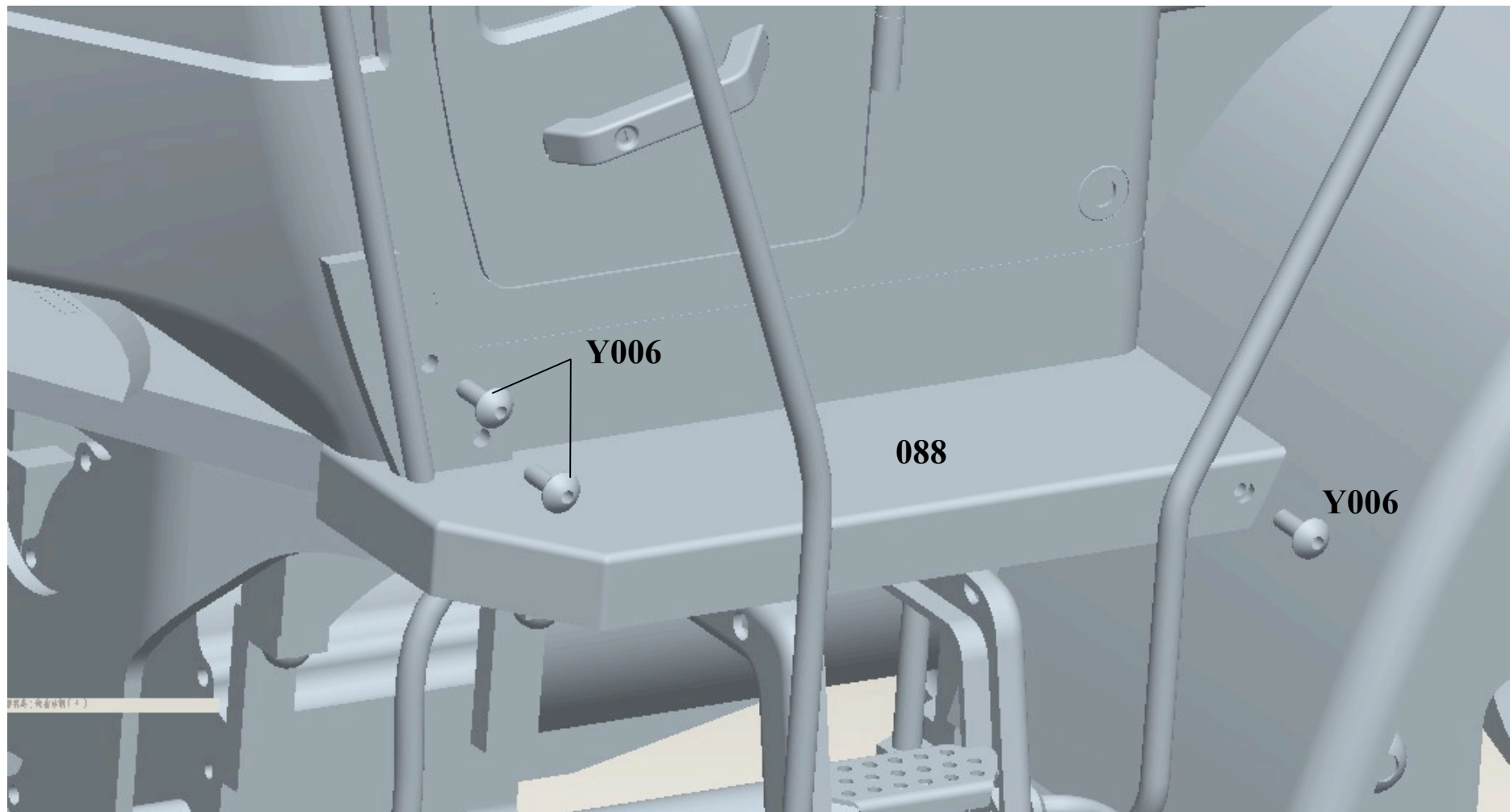


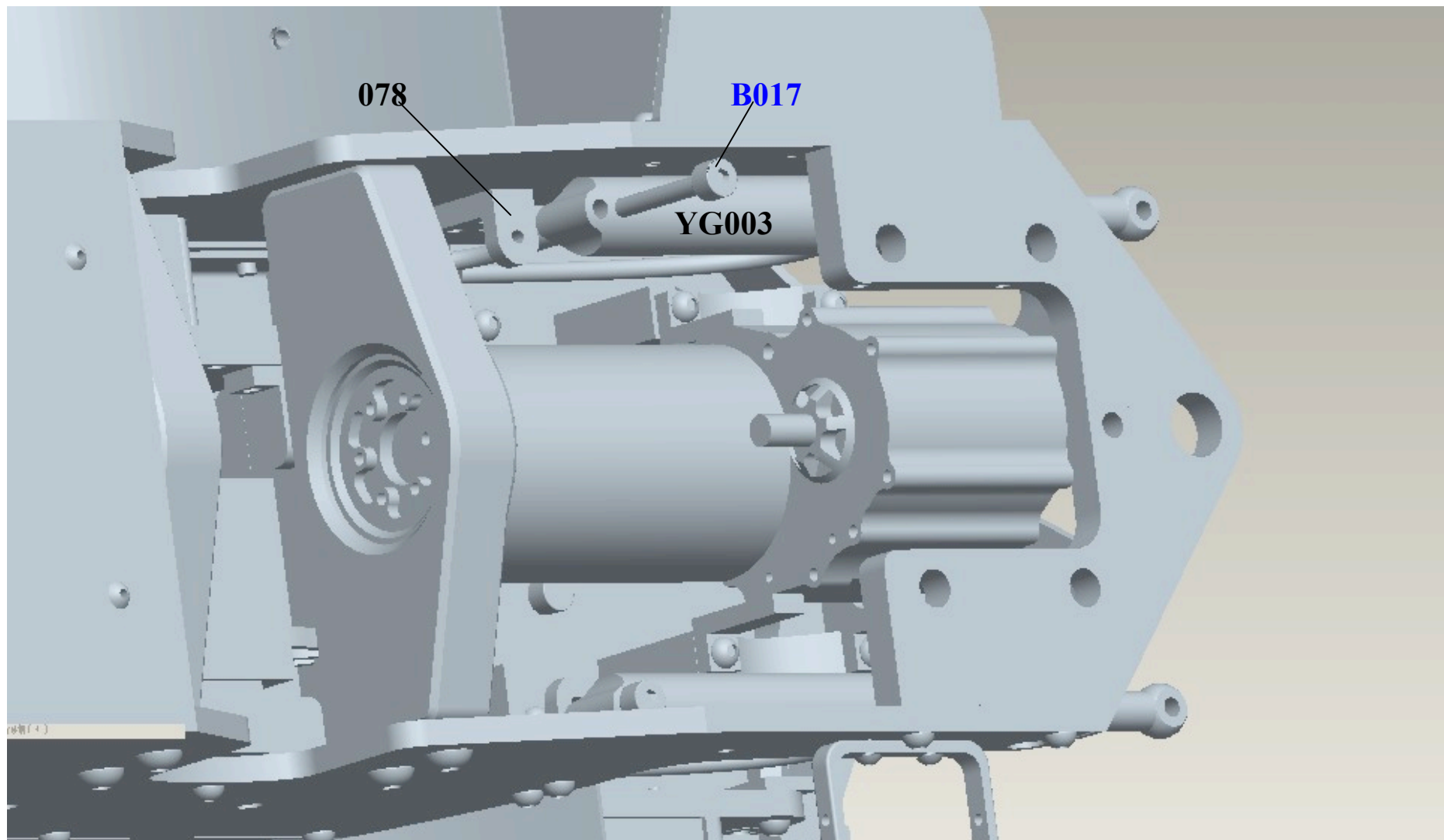


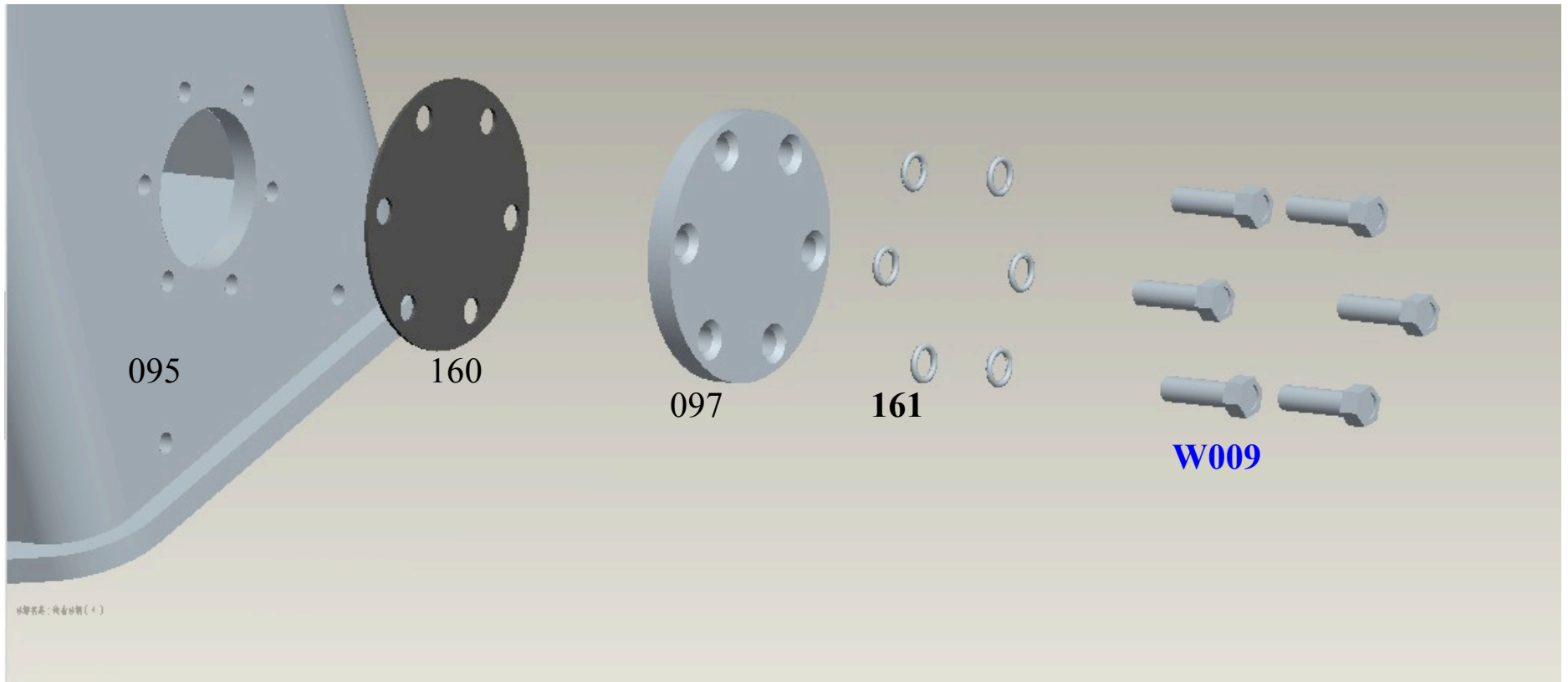


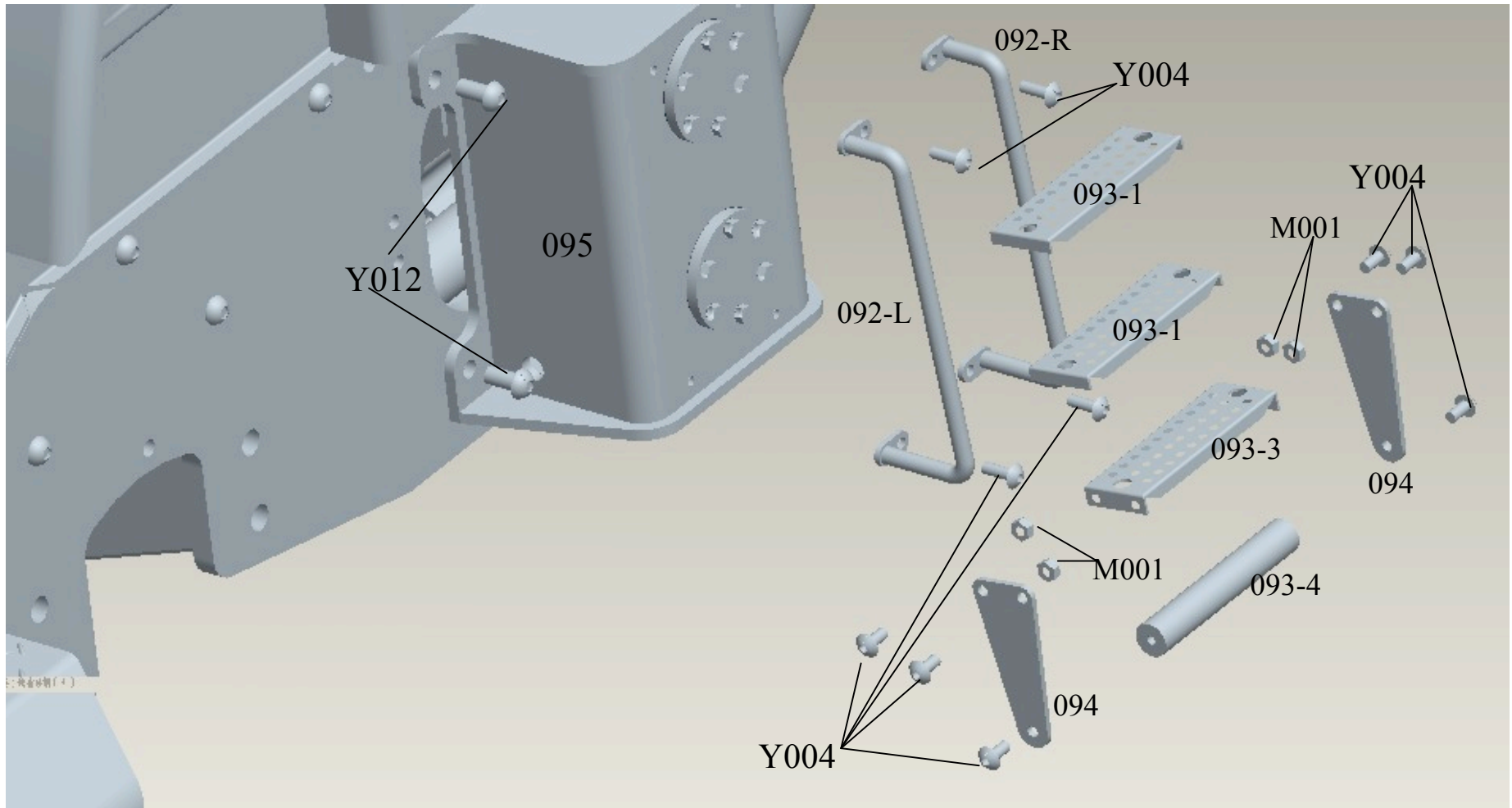


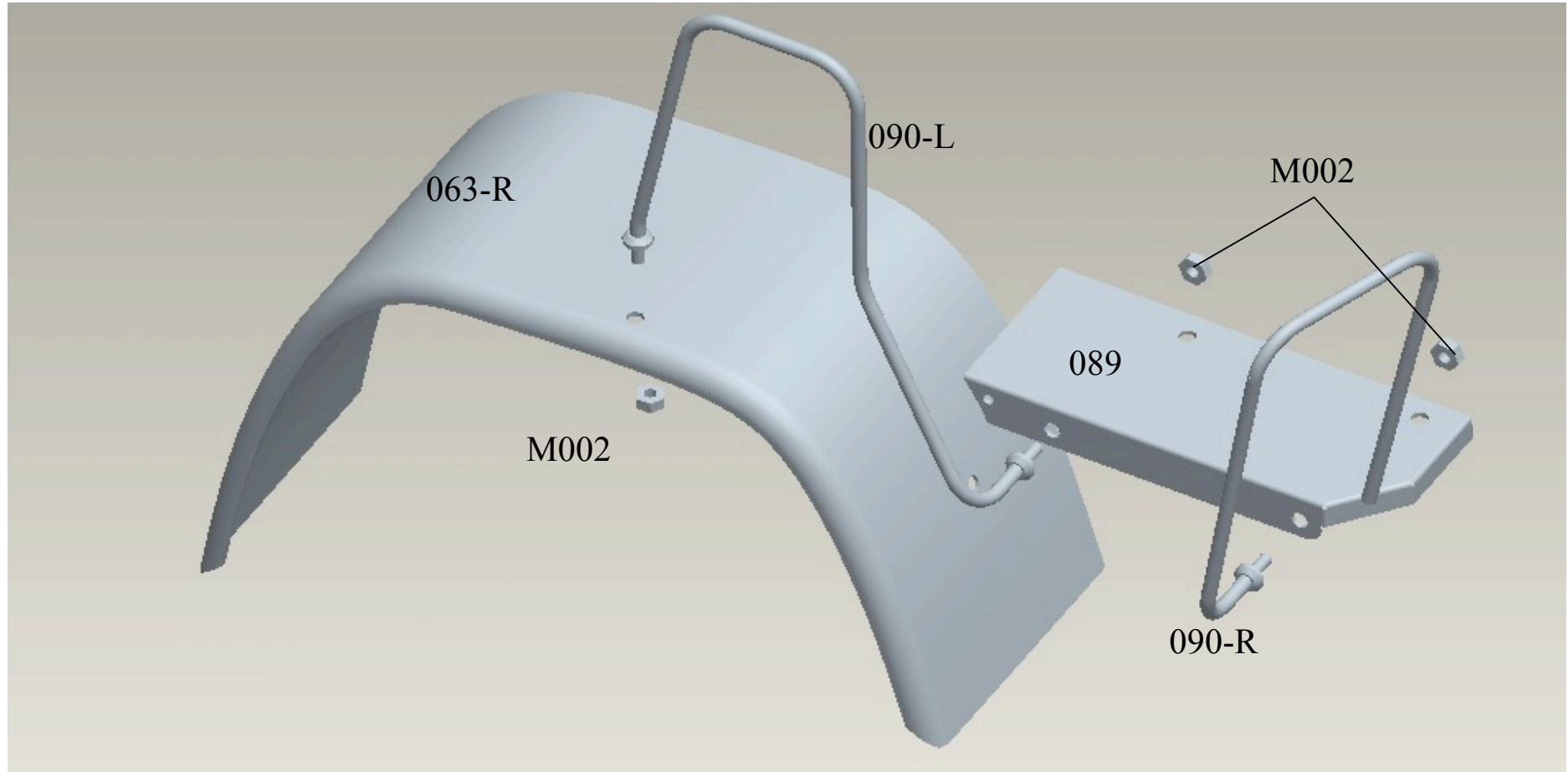


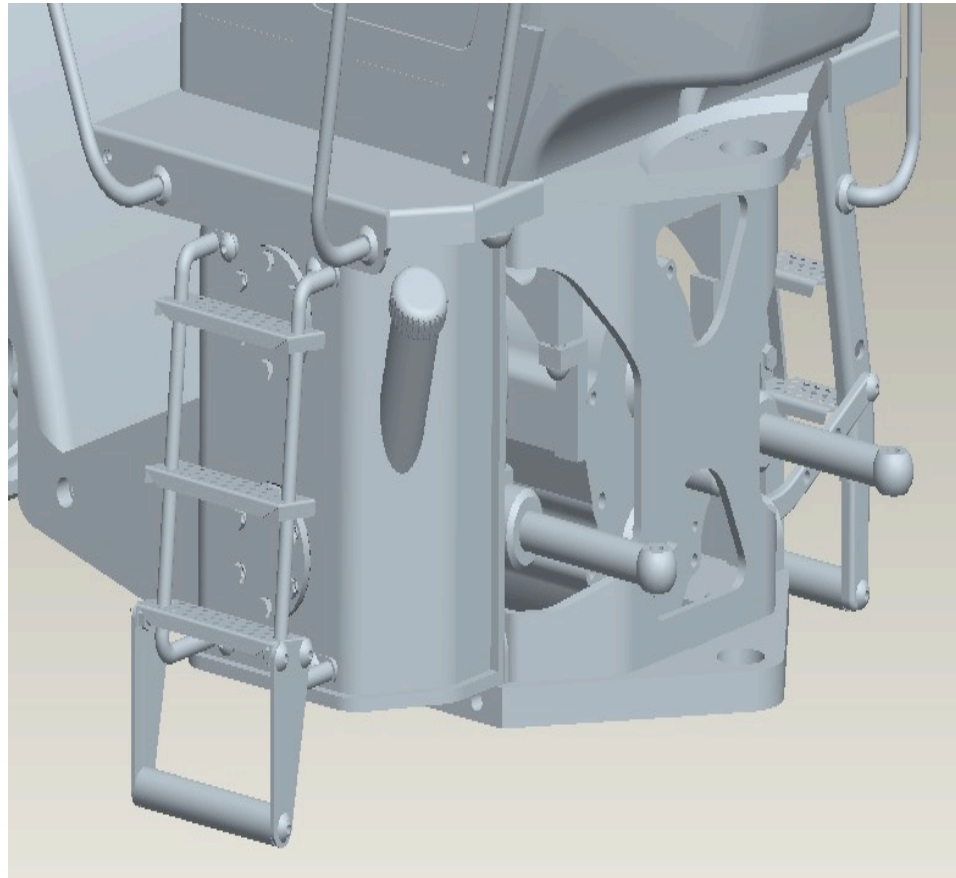
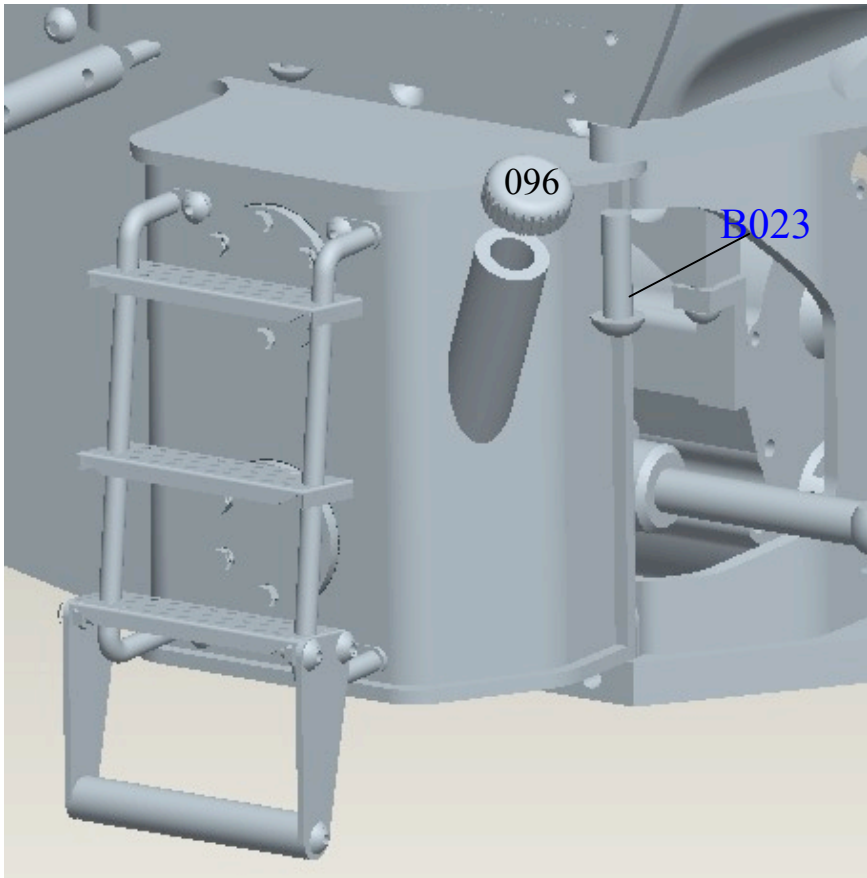


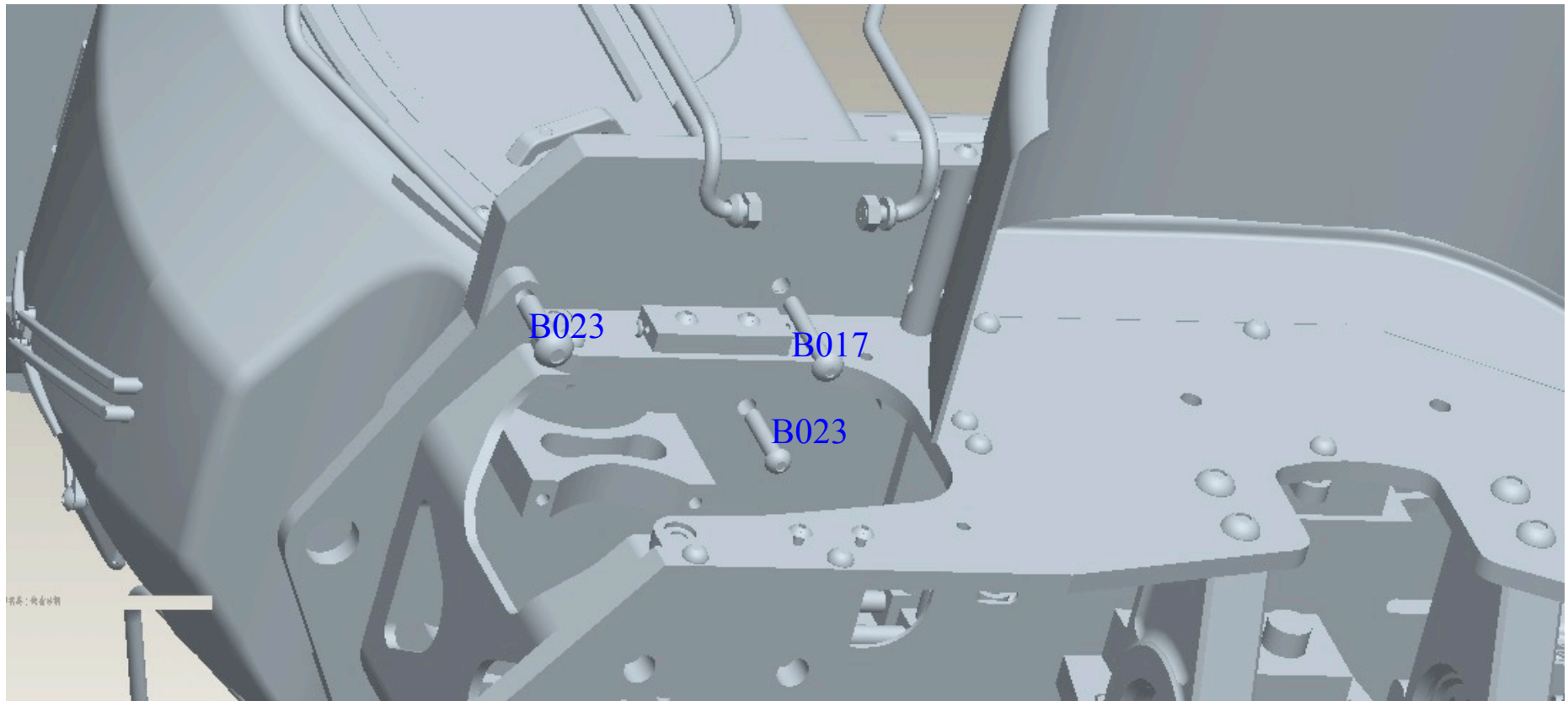


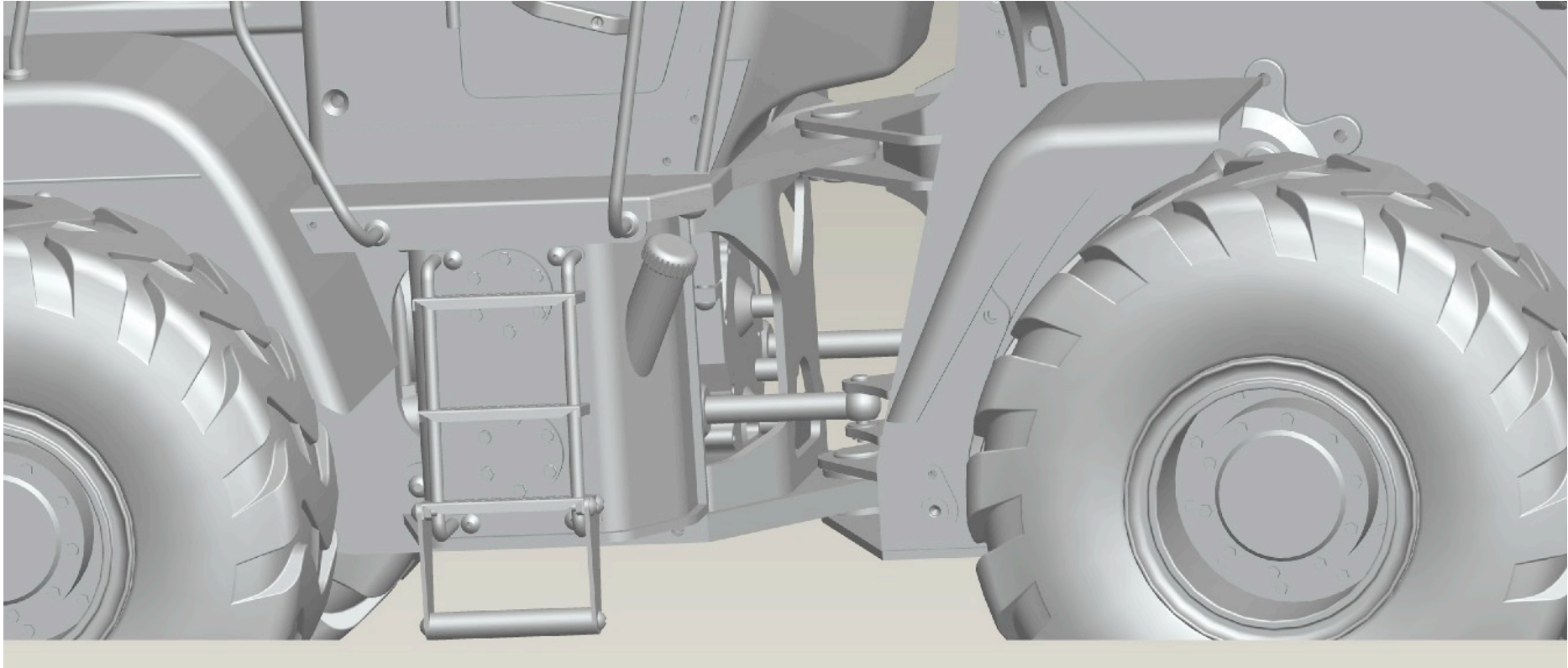


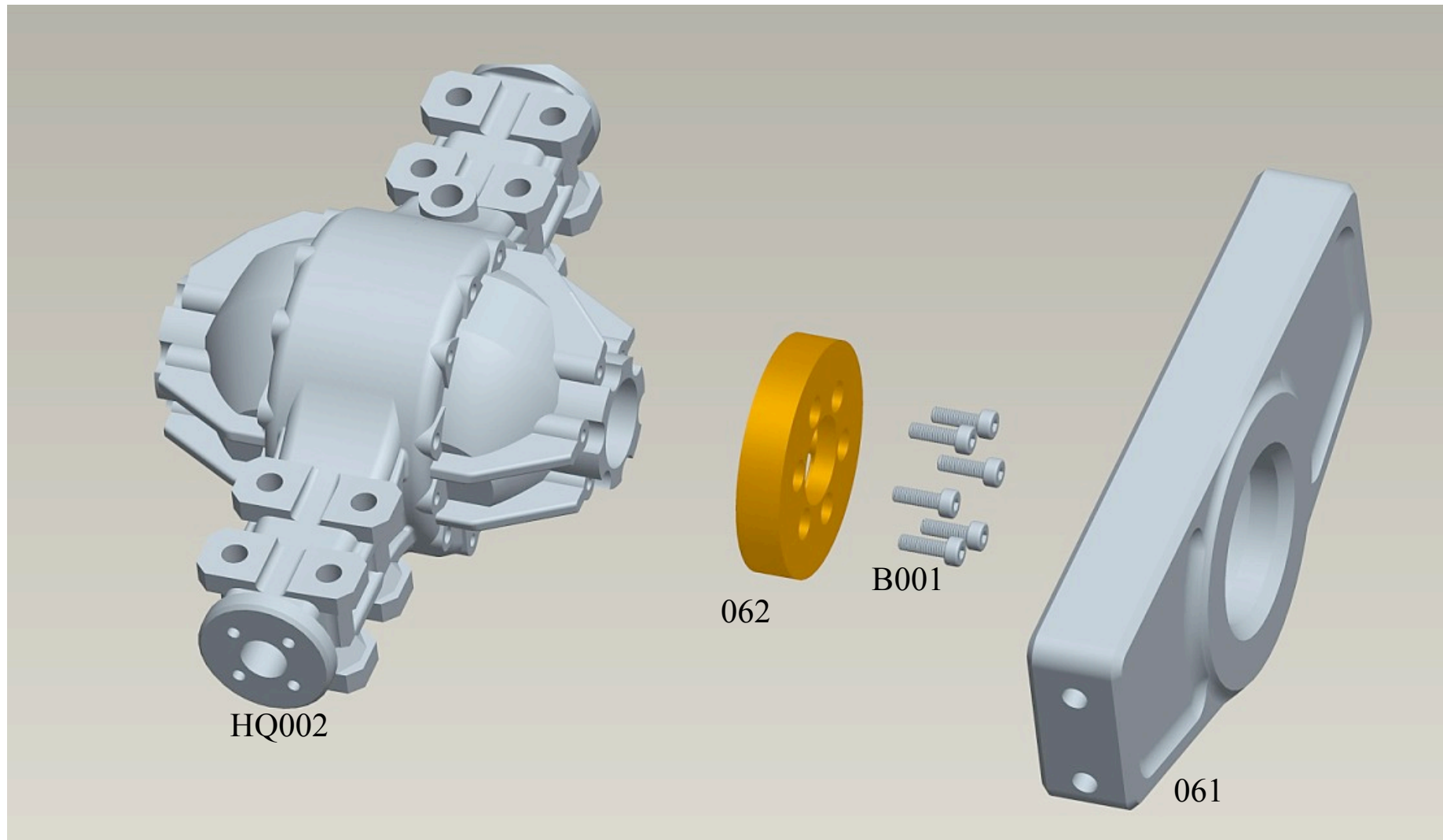


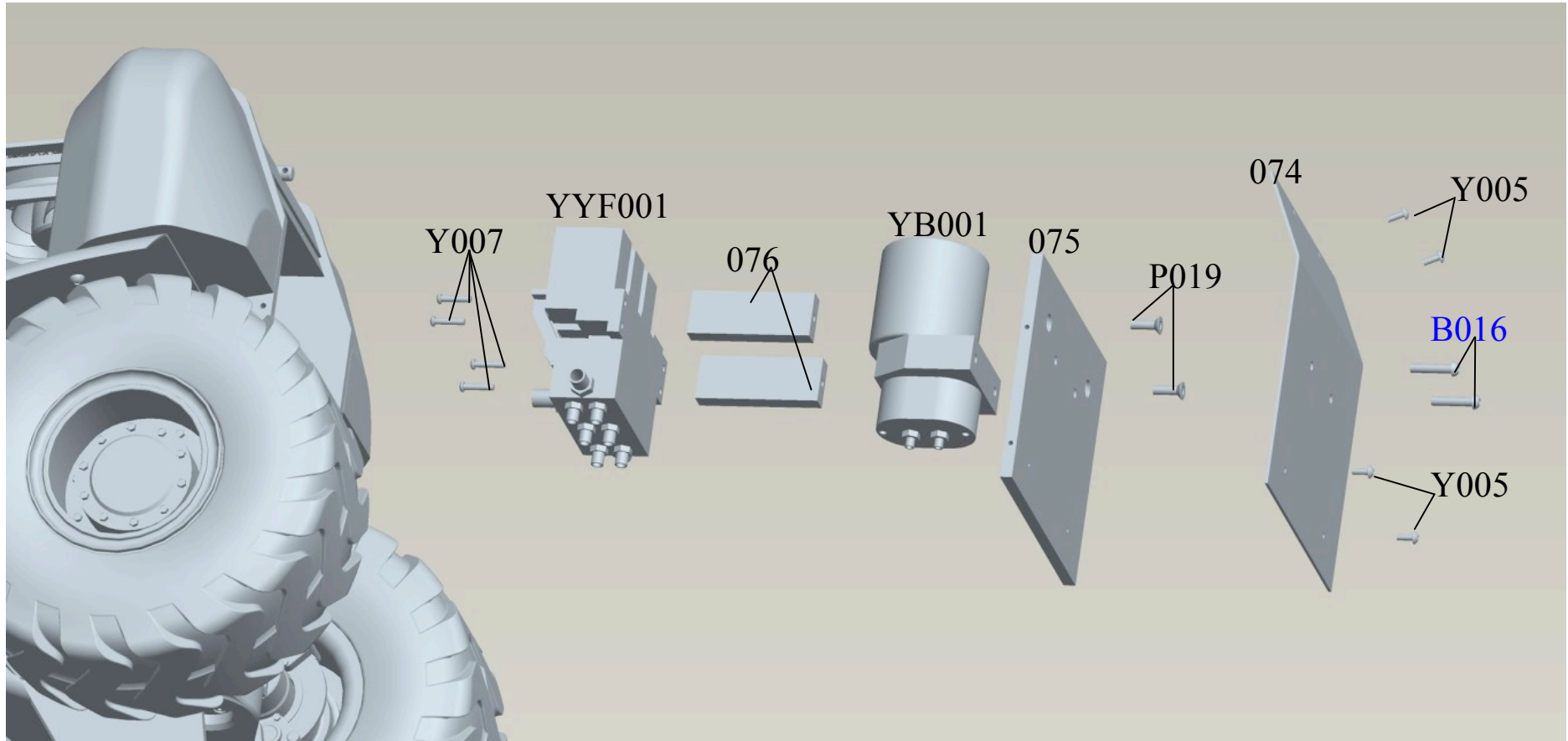


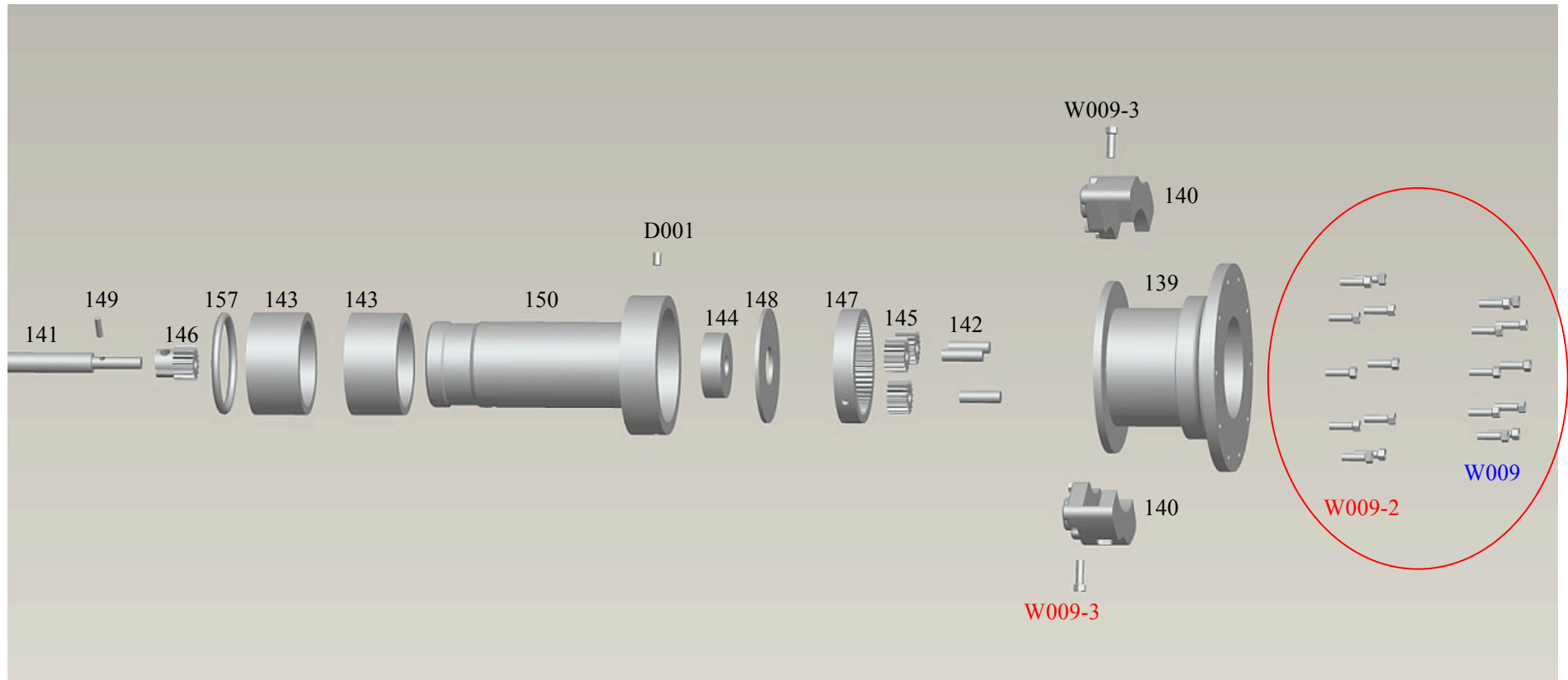


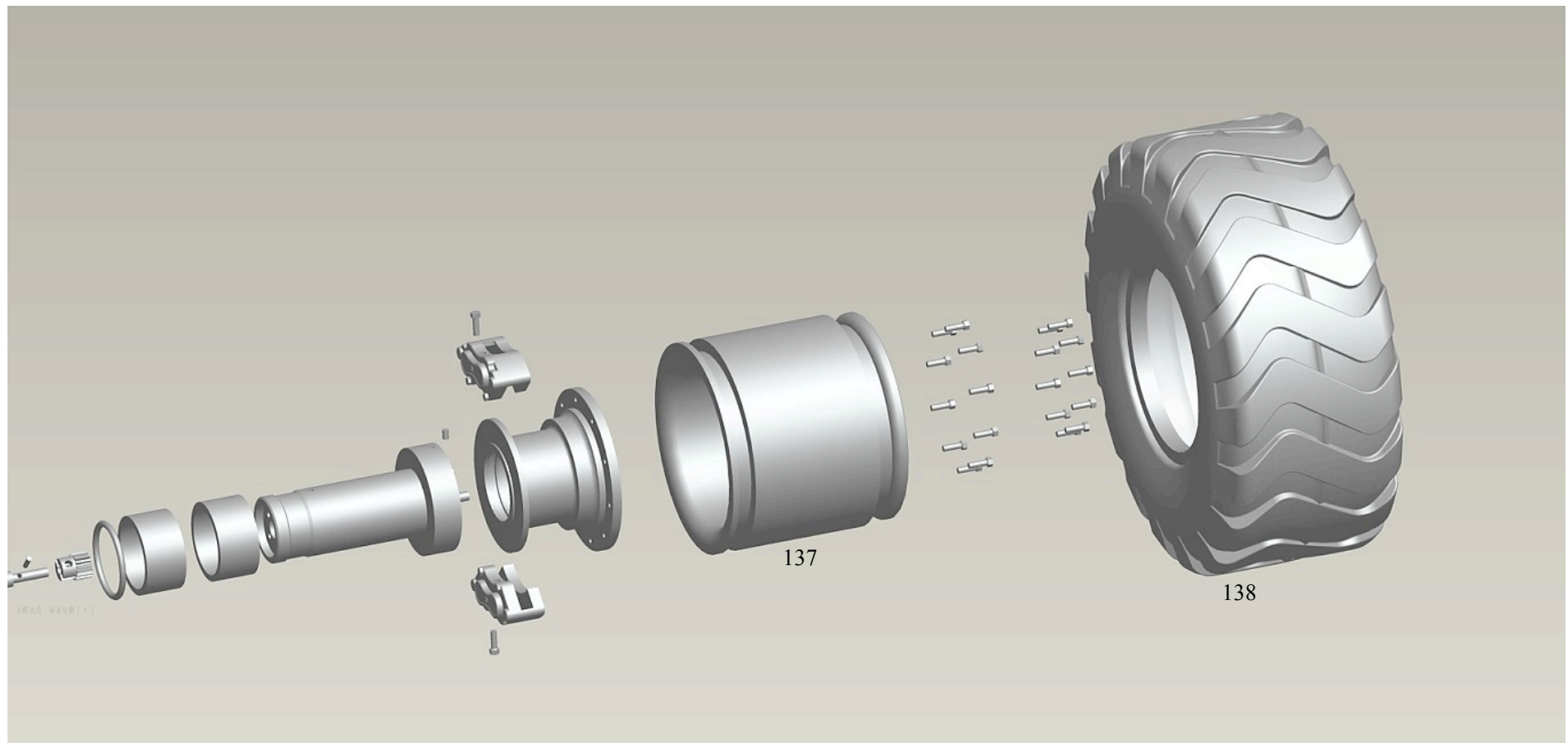


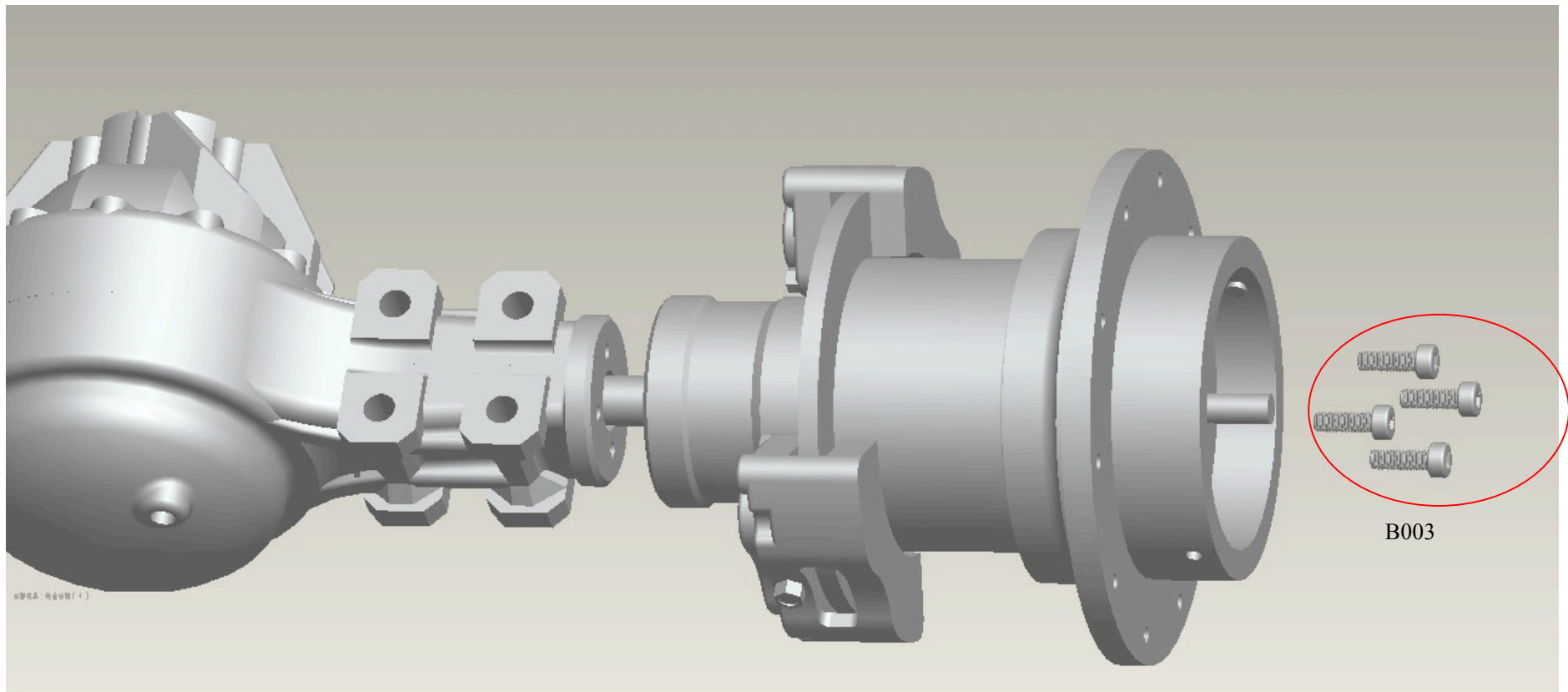




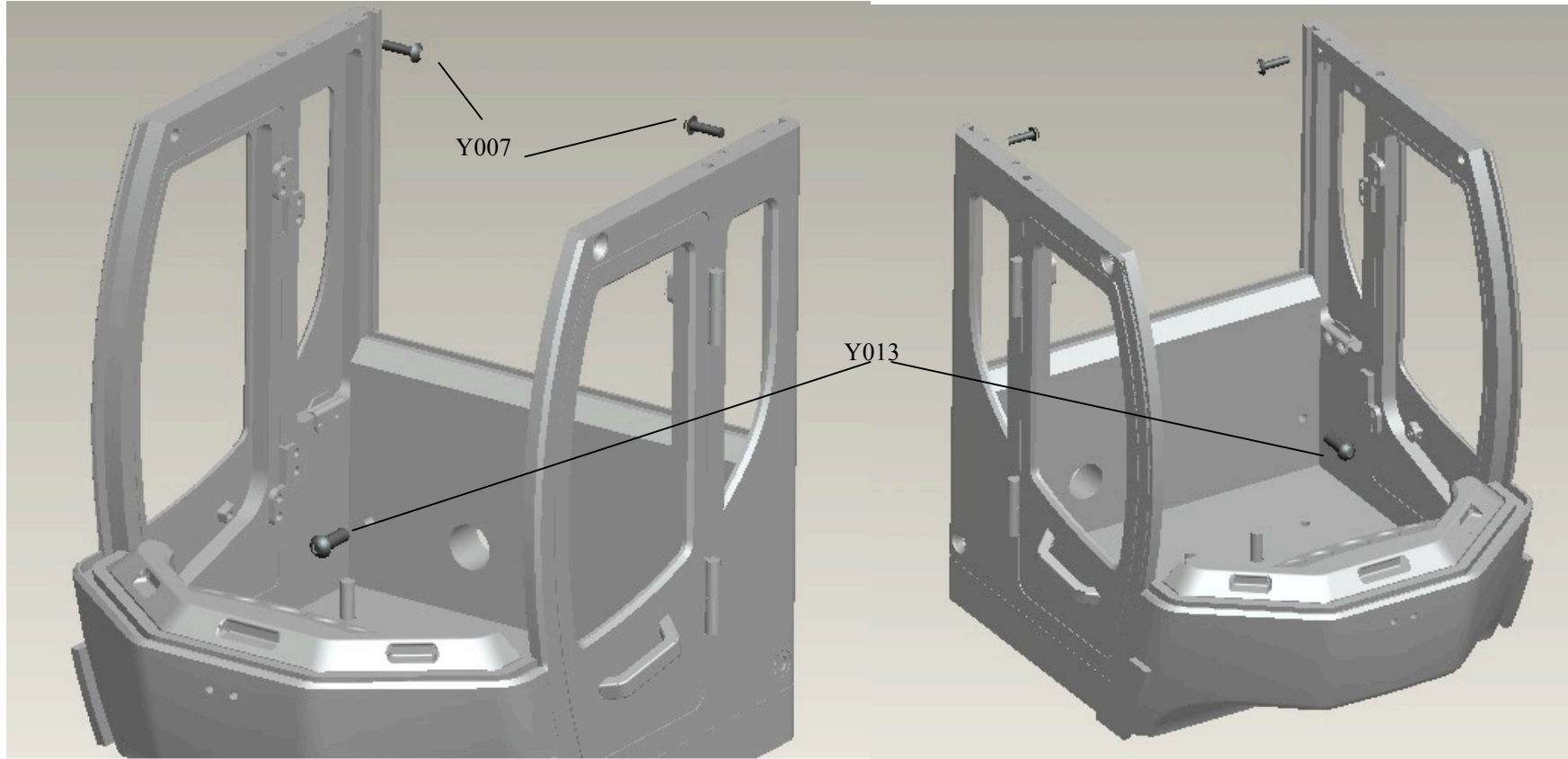


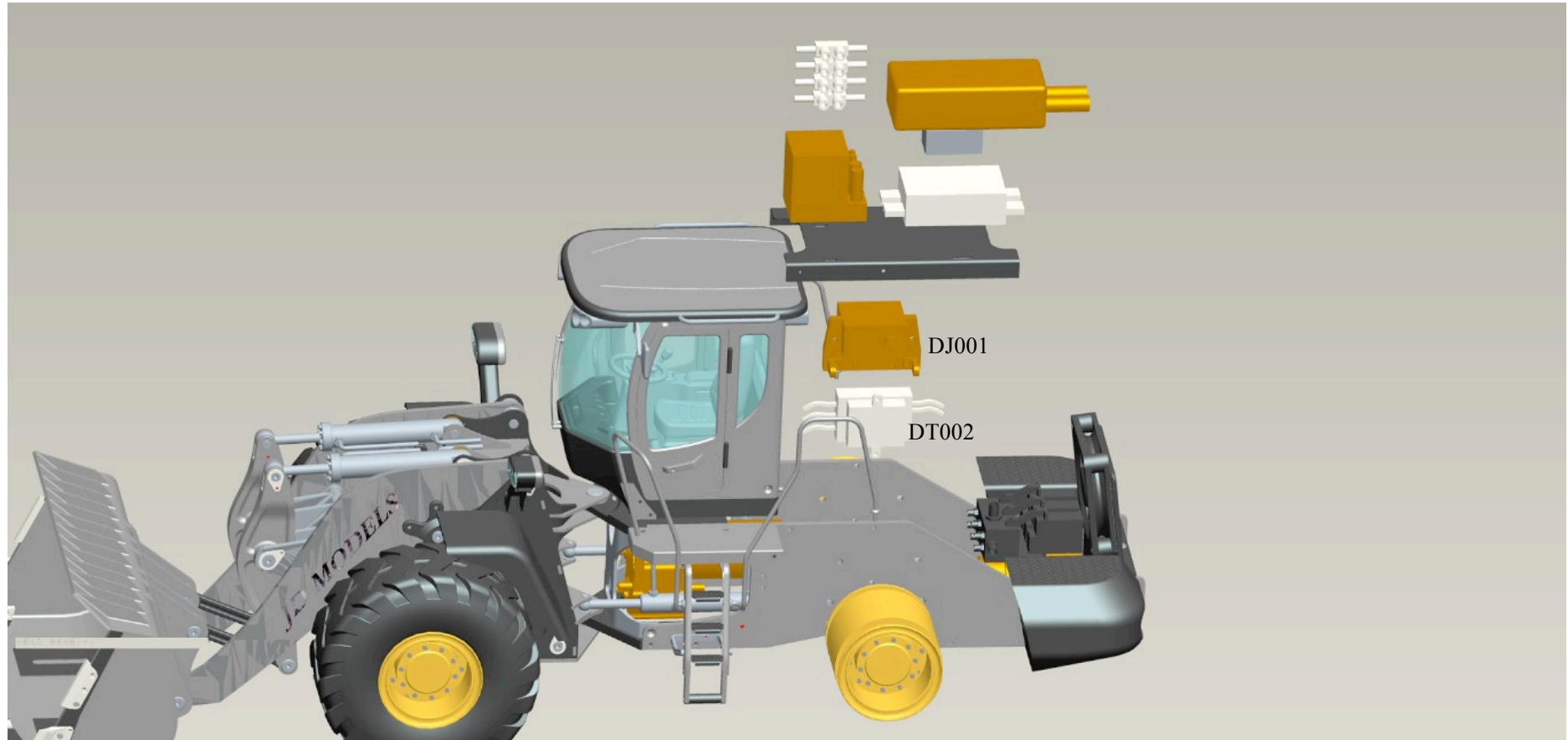


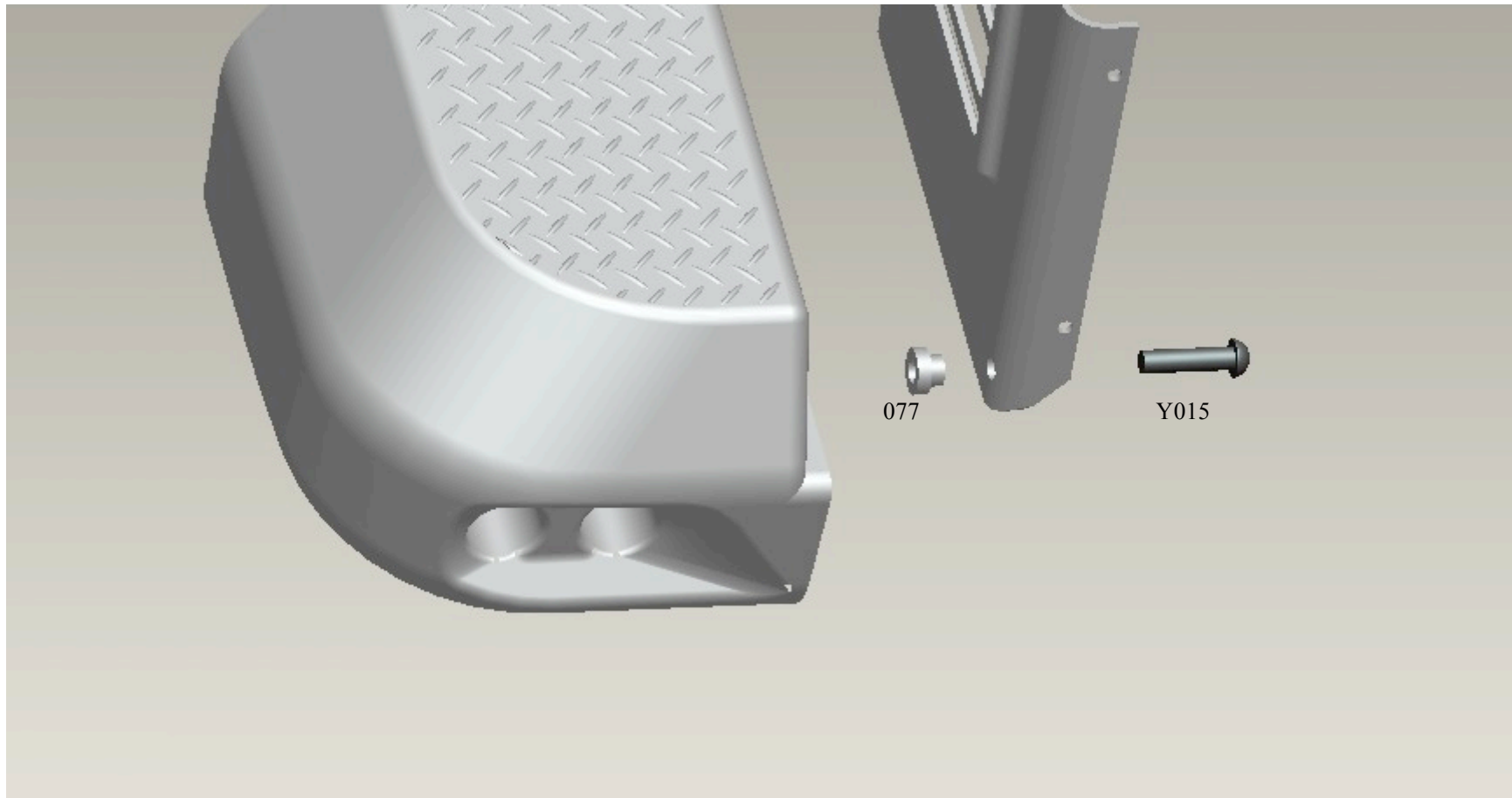


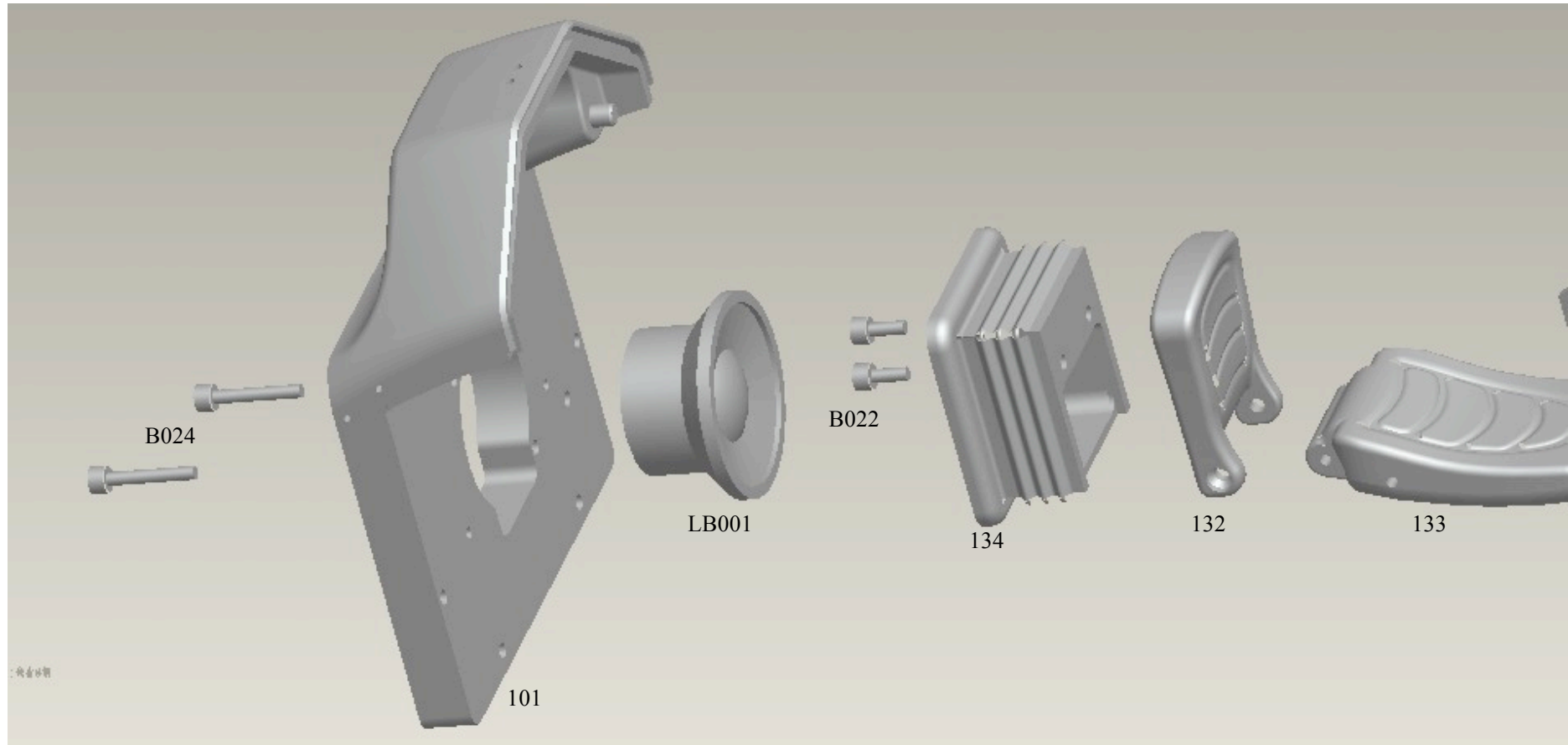


B003









Attaching the Bucket to the arms:

1. Locate the Bag with the Screws, Pins and Brackets



2. Insert the Pin in the holes of the Arm and Cylinder with the groove (in pin) on the Outside of the Arm Flange. Make sure the groove is exposed.



4. Add Thread Lock (Blue) to the screw.



3. Hang the bracket in the groove and then slide the pin back so that the bracket is flush against the flange.



5. Line up the bracket with the hole and tighten the screw.

